# Mixin modules in a call-by-value setting 

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The ML module system provides powerful parameterization facilities, but lacks the ability to split mutually recursive definitions across modules and provides insufficient support for incremental programming. A promising approach to solve these issues is Ancona and Zucca's mixin module calculus $C M S$. However, the straightforward way to adapt it to ML fails, because it allows arbitrary recursive definitions to appear at any time, which ML does not otherwise support. In this paper, we enrich $C M S$ with a refined type system that controls recursive definitions through the use of dependency graphs. We then develop and prove sound a separate compilation scheme, directed by dependency graphs, that translates mixin modules down to a call-by-value $\lambda$-calculus extended with a non-standard let rec construct.

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## 1. INTRODUCTION

Modular programming and code reuse are easier if the programming language provides adequate features to support them. Three important such features are (1) parameterization, which allows reusing a module in different contexts; (2) overriding and late binding, which supports incremental programming by refinement of existing modules; and (3) cross-module recursion, which allows definitions to be spread across several modules, even if they mutually refer to each other. Many programming languages provide two of these features, but not all three: class-based object-oriented languages provide (2) and (3), but are weak on parameterization (1);

[^0]conventional linkers, as well as linking calculi [Cardelli 1997], have cross-module recursion built in, and sometimes provide facilities for overriding, but lack parameterization; finally, ML functors and Ada generics provide powerful parameterization mechanisms, but prohibit cross-module recursion and offer no direct support for late binding.

The concept of mixins, first introduced as a generalization of inheritance in classbased OO languages [Bracha and Cook 1990], then extended to a family of module systems [Duggan and Sourelis 1996; Ancona and Zucca 2002; Flatt and Felleisen 1998; Wells and Vestergaard 2000], offers a promising and elegant solution to this problem. A mixin is a collection of named components, either defined (bound to a definition) or deferred (declared without definition). The basic operation on mixins is the sum, which takes two mixins and connects the defined components of one with the similarly-named deferred components of the other; this provides natural support for cross-mixin recursion. A mixin is named and can be summed several times with different mixins; this allows powerful parameterization, including but not restricted to an encoding of ML functors. Finally, the mixin calculus of Ancona and Zucca [2002] supports both late binding and early binding of defined components, along with deleting and renaming operations, thus providing excellent support for incremental programming.

Our long-term goal is to extend the ML module system with mixins, taking the $C M S$ calculus [Ancona and Zucca 2002] as a starting point. There are two main issues: one, which we leave for future work, is to support type components in mixins; the other, which we address in this paper, is to equip $C M S$ with a call-byvalue semantics consistent with that of the core ML language. Shifting $C M S$ from its original call-by-name semantics to a call-by-value semantics requires a precise control of recursive definitions created by mixin sum. The call-by-name semantics of $C M S$ puts no restrictions on recursive definitions, allowing ill-founded ones such as let rec $\mathrm{x}=2 * \mathrm{y}$ and $\mathrm{y}=\mathrm{x}+1$, causing the program to diverge if the value of x or y is needed. This issue was not present in the original concept of mixin, which allowed only syntactic values as mixin components. We call mixins with arbitrary components mixin modules, hereafter simply referred to as mixins when there is no ambiguity.

In an ML-like, call-by-value setting, recursive definitions are statically restricted to syntactic values, e.g. let rec $f=\lambda x \ldots$ and $g=\lambda y \ldots$ This approach provides stronger guarantees (ill-founded recursions are detected at compile-time rather than at run-time), and supports more efficient compilation of recursive definitions. Extending these two desirable properties to mixin modules in the presence of separate compilation [Cardelli 1997; Leroy 1994] is challenging: illegal recursive definitions can appear a posteriori when we take the sum $A+B$ of two mixin modules, at a time where only the signatures of $A$ and $B$ are known, but not their implementations.

The solution we develop here is to enrich the CMS type system, adding graphs in mixin signatures to represent the dependencies between the components. The resulting typed calculus, called $C M S_{v}$, guarantees that recursive definitions created by mixin sum evaluate correctly under a call-by-value regime, yet leaves considerable flexibility in composing mixins. We then provide a type-directed, separate
compilation scheme for $C M S_{v}$. The target of this compositional translation is $\lambda_{B}$, a simple call-by-value $\lambda$-calculus with a non-standard let rec construct in the style of Boudol [2003]. Finally, we prove that the compilation of a type-correct $C M S_{v}$ mixin is well typed in a sound, non-standard type system for $\lambda_{B}$ that generalizes that of Boudol [2003], thus establishing the soundness of our approach.

The remainder of the paper is organized as follows. Section 2 gives a high-level overview of the $C M S$ and $C M S_{v}$ mixin calculi, and explains the recursion problem. Section 3 defines the syntax and typing rules for $C M S_{v}$, our call-by-value mixin calculus. The compilation scheme (from $C M S_{v}$ to $\lambda_{B}$ ) is presented in section 4. In section 5 , we equip $\lambda_{B}$ with a type system guaranteeing the proper call-byvalue evaluation of recursive definitions, and use it to show the correctness of the compilation scheme. We review related work in section 6 , and conclude in section 7 . Detailed proofs are provided in appendix.

## 2. OVERVIEW

### 2.1 The $C M S$ calculus of mixins

We start this paper by an overview of the $C M S$ module calculus of Ancona and Zucca [2002], using an ML-like syntax for readability. A basic mixin is similar to an ML structure, but may contain "holes":

```
mixin Even = mix
    ? val odd: int -> bool (* odd is deferred *)
    let even = \lambdax. x = 0 or odd(x-1) (* even is defined *)
end
```

In other terms, a mixin consists of defined components, let-bound to an expression, and deferred components, declared but not yet defined. The fundamental operator on mixins is the sum, which combines the components of two mixins, connecting defined and deferred components having the same names. For example, if we define Odd as

```
mixin Odd = mix
    ? val even: int -> bool
    let odd = \lambdax. x > 0 and even(x-1)
end
```

the result of mixin Nat $=$ Even + Odd is equivalent to writing

```
mixin Nat = mix
    let even = \lambdax. x = 0 or odd(x-1)
    let odd = \x. x > 0 and even(x-1)
end
```

As in class-based languages, all defined components of a mixin are mutually recursive by default; thus, the above should be read as the ML structure

```
module Nat = struct
    let rec even = \lambdax. x = 0 or odd(x-1)
        and odd = \lambdax. x > 0 and even(x-1)
end
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```

Another commonality with classes is that defined components are late bound by default: the definition of a component can be overridden later, and other definitions that refer to this component will "see" the new definition. The overriding is achieved in two steps: first, deleting the component via the $\backslash$ operator, then redefining it via a sum. For instance,

```
mixin Nat' = (Nat \ even) + (mix let even = \lambdax. x mod 2 = 0 end)
```

is equivalent to the direct definition

```
mixin Nat' = mix
    let even = \lambdax. x mod 2 = 0
    let odd = \lambdax. x > 0 and even(x-1)
end
```

Early binding (definite binding of a defined name to an expression in all other components that refer to this name) can be achieved via the "!" operator (pronounced "freeze"). For instance, Nat ! odd is equivalent to

```
mix
    let even \(=\) let odd \(=\lambda x . x>0\) and even \((x-1)\) in
                    \(\lambda \mathrm{x} . \mathrm{x}=0\) or \(\operatorname{odd}(\mathrm{x}-1)\)
    let odd \(=\lambda \mathrm{x} . \mathrm{x}>0\) and even \((\mathrm{x}-1)\)
end
```

For convenience, our $C M S_{v}$ calculus also provides a close operator that freezes all components of a mixin in one step. Projections (extracting the value of a mixin component) are restricted to closed mixins, to ensure that they do not need to trigger any computations.

A component of a mixin can itself be a mixin. Not only does this provide MLstyle nested mixins, but it also supports a general encoding of ML functors [Ancona and Zucca 1999]. Consider the following ML functor definition and applications.

```
module F = functor (X : S) -> struct ... end
module R = F(A)
module S = F(B)
```

We can achieve the same effect in $C M S_{v}$ by representing F as a mixin with a deferred mixin component representing its formal parameter, then summing it twice with the actual arguments A and B .

```
mixin F = mix
    ? mixin Arg : S
    mixin X = Arg
    mixin Res = mix ... end
end
mixin R = close(F + mix mixin Arg = A end).Res
mixin S = close(F + mix mixin Arg = B end).Res
```

This encoding extends to curried and higher-order functors. For instance, the curried functor

```
module G = functor (X : S) -> functor (Y : S') -> struct ... end
```

is encoded as follows:

```
mixin G = mix
    ? mixin Arg : S
    mixin X = Arg
    mixin Res = mix
        ? mixin Arg : S'
        mixin Y = Arg
        ..
    end
end
```

In the latter example, the need for the additional bindings $X=\operatorname{Arg}$ and $Y=\operatorname{Arg}$ becomes clear: the formal parameter of a functor must be bound to a fixed, conventional name (here Arg ) so that clients of the functor can apply it without knowing the name of its formal parameter; at the same time, a functor body (the . . . in the example above) may need to refer to several functor parameters, requiring them to have distinct, $\alpha$-convertible names. A similar trick is used to encode the $\lambda$-calculus into the $\varsigma$-calculus of Abadi and Cardelli [1996].

### 2.2 Controlling recursive definitions

It is well known that general recursive definitions, whose right-hand sides involve arbitrary computation, require call-by-name or call-by-need (lazy) evaluation, via on-demand unfolding. If the recursive definition is not well founded, as in let rec $\mathrm{x}=\mathrm{y}+1$ and $\mathrm{y}=2 * \mathrm{x}$, the program will diverge the first time the value of x or y is needed. In contrast, call-by-value evaluation of recursive definitions is usually allowed only if the right-hand sides are syntactic values (e.g. $\lambda$-abstractions or constants), thus ruling out the example above. In return, the programmer obtains the guarantee that the recursive definition is well-founded, evaluates in one step, and will not cause divergence nor re-computation when the recursively-defined identifiers are used.

This semantic issue is exacerbated by mixins, which are in essence big mutual let rec definitions. Worse, ill-founded recursive definitions such as the above can appear not only when defining a basic mixin such as

```
mixin Bad = close(mix let x = y + 1 let y = x * 2 end)
```

but also a posteriori when combining two innocuous-looking mixins:

```
mixin OK1 = mix ? val y : int let x = y + 1 end
mixin OK2 = mix ? val x : int let y = x * 2 end
mixin Bad = close(OK1 + OK2)
```

Although OK1 and OK2 contain no ill-founded recursions, the sum OK1 + OK2 contains one. If the definitions of OK1 and OK2 are known when we type-check and compile their sum, we can simply expand OK1 + OK2 into an equivalent monolithic mixin and reject the faulty recursion. But in a separate compilation setting, OK1 + OK2 can be compiled in a context where the definitions of OK1 and OK2 are not known, but only their signatures are. Then, the ill-founded recursion cannot be detected. This is the major problem we face in extending ML with mixins.

A partial solution to this problem is to detect ill-founded recursions at execution time, and generate a run-time error. This can be achieved by lazy evaluation of the right-hand sides of recursive definitions. Operationally, to evaluate a recursive definition $x_{1}=e_{1}$ and $\ldots$ and $x_{n}=e_{n}$, each $x_{i}$ is bound to a thunk for $e_{i}$; these thunks are then evaluated in sequence, memoizing their values; if the evaluation of $e_{i}$ needs the value of $x_{j}$ and the thunk $e_{j}$ is not yet computed, its evaluation is performed and memoized at that time; finally, the ill-founded case where the evaluation of $e_{i}$ requires its own value via a reference to $x_{i}$ is detected and reported as a run-time error. This approach is used for evaluating recursive modules in Moscow ML [Russo 2001]. A simplification of this approach is used to evaluate the letrec construct of Scheme: the recursively-defined variables $x_{i}$ are initialized with a special "do not use" value; the right-hand sides $e_{i}$ are evaluated in sequence, raising an error if a variable evaluates to the "do not use" value; and finally the initial variable values are updated in place with the values of the right-hand sides. While practical and easy to implement, these approaches have the drawback that ill-founded recursive definitions (as in the Bad example above) are not detected until run-time. To increase program safety, we would much prefer to detect ill-founded definitions statically, at compile time.

To achieve this goal, our approach consists in enriching mixin signatures with graphs representing the dependencies between components of a mixin, and rely on these graphs to detect statically ill-founded recursive definitions. For example, the Nat and Bad mixins shown above have the following dependency graphs:


An edge $X \xrightarrow{\chi} Y$ expresses that $X$ is used by the definition of $Y$. Edges labeled 0 represent an immediate dependency: the value of the source node is needed to compute that of the target node. Edges labeled 1 represent a delayed dependency, occurring under at least one $\lambda$-abstraction; thus, the value of the target node can be computed without knowing that of the source node. Ill-founded recursions manifest themselves as cycles in the dependency graph involving at least one " 0 " edge. Thus, the correctness criterion for a mixin is, simply: all cycles in its dependency graph must be composed of " 1 " edges only. Hence, Nat is correct, while Bad is rejected.
(Notice that the weaker criterion "all cycles contain at least one edge labeled 1 " is incorrect, since it would allow ill-founded definitions such as let rec $\mathrm{f}=\lambda \mathrm{x}$. $x+y$ and $y=f 0$.)

The power of dependency graphs becomes more apparent when we consider mixins that combine recursive definitions of functions and immediate computations that sit outside the recursion. (This situation typically arises when a module involved in a mutually recursive definition needs to perform initializing computations.)

```
mixin M1 = mix
    ? val g : ...
    let f = \lambdax. ...g...
    let u = f 0
end
```

```
mixin M2 = mix
    ? val f : ...
    let g = \lambdax. ...f...
    let v = g 1
end
```

| Core terms: | $\begin{aligned} C::= & x \mid \text { cst } \\ & \|\lambda x . C\| C_{1} C_{2} \\ & \mid E . X \end{aligned}$ | variable, constant abstraction, application component projection |
| :---: | :---: | :---: |
| Mixin terms: | $\begin{aligned} E::= & C \\ & \mid\langle\iota ; o\rangle \\ & \mid E_{1}+E_{2} \\ & \mid E[X \leftarrow Y] \\ & \mid E!X \\ & \mid E \backslash X \\ & \mid \operatorname{close}(E) \end{aligned}$ | core term mixin structure sum rename $X$ to $Y$ <br> freeze $X$ <br> delete $X$ <br> close |
| Input assignments: | $\iota::=x_{i} \stackrel{i \in I}{\longmapsto} X_{i}$ | $\iota$ injective |
| Output assignments: | $o::=X_{i} \stackrel{i \in I}{\longmapsto} E_{i}$ |  |
| Core types: | $\tau::=$ int $\mid$ bool $\mid \tau \rightarrow \tau$ |  |
| Mixin types: | $\begin{aligned} \mathcal{T}::= & =\tau \\ & \mid\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\} \end{aligned}$ | core type mixin signature |
| Type assignments: <br> Dependency graphs: | $\begin{aligned} & \mathcal{O}::=X_{i} \stackrel{i \in I}{\mapsto} \mathcal{T}_{i} \\ & \mathcal{D} \quad(\text { see section 3.2) } \end{aligned}$ |  |

Fig. 1. Syntax of $C M S_{v}$
The dependency graph for the sum M1 + M2 is:


It satisfies the correctness criterion, thus this definition is accepted. Other systems that record a global "valuability" flag on each signature, such as the recursive modules of [Crary et al. 1999], would reject this definition.

## 3. THE $C M S_{V}$ CALCULUS

We now define formally the syntax and typing rules of $C M S_{v}$, our call-by-value variant of $C M S$.

### 3.1 Syntax

The syntax of $C M S_{v}$ terms and types is defined in Figure 1. Here, $x$ ranges over a countable set Vars of ( $\alpha$-convertible) variables, while $X$ ranges over a countable set Names of (non-convertible) names used to identify mixin components.

Although our module system is largely independent of the core language, for the sake of specificity we use a standard simply-typed $\lambda$-calculus with constants as core language. Core terms can refer by name to a component of a mixin structure, via the notation E.X.

Mixin terms include core terms (proper stratification of the language is enforced by the typing rules), structure expressions building a mixin from a collection of components, and the various mixin operators mentioned in section 2: sum, rename, freeze, delete and close.

A mixin structure $\langle\iota ; o\rangle$ is composed of an input assignment $\iota$ and an output

## Free variables:

$$
\begin{aligned}
F V(x) & =\{x\} & F V(c s t) & =\emptyset \\
F V(\lambda x . C) & =F V(C) \backslash\{x\} & F V\left(C_{1} C_{2}\right) & =F V\left(C_{1}\right) \cup F V\left(C_{2}\right) \\
F V(\langle\iota ; o\rangle) & =F V(o) \backslash \operatorname{dom}(\iota) & F V\left(X_{i} \stackrel{i \in I}{\mapsto} E_{i}\right) & =\bigcup_{i \in I} F V\left(E_{i}\right) \\
F V\left(E_{1}+E_{2}\right) & =F V\left(E_{1}\right) \cup F V\left(E_{2}\right) & F V(E!X) & =F V(E) \\
F V(E . X) & =F V(E) & F V(E[X \leftarrow Y]) & =F V(E) \\
F V(E \backslash X) & =F V(E) & F V(\operatorname{close}(E)) & =F V(E)
\end{aligned}
$$

## Substitution:

$$
\begin{aligned}
y\{x \leftarrow E\} & =E \text { if } y=x, y \text { otherwise } \\
c s t\{x \leftarrow E\} & =\text { cst } \\
\lambda y \cdot C\{x \leftarrow E\} & =\lambda y . C\{x \leftarrow E\} \text { if } y \notin F V(E) \cup\{x\} \\
\left(C_{1} C_{2}\right)\{x \leftarrow E\} & =C_{1}\{x \leftarrow E\} C_{2}\{x \leftarrow E\} \\
\langle\iota ; o\rangle\{x \leftarrow E\} & =\langle\iota ; o\{x \leftarrow E\}\rangle \text { if } x \notin \operatorname{dom}(\iota) \\
\left(X_{i} \stackrel{i \in I}{\mapsto} E_{i}\right)\{x \leftarrow E\} & =X_{i} \quad i \in I E_{i}\{x \leftarrow E\} \\
\left(E_{1}+E_{2}\right)\{x \leftarrow E\} & =E_{1}\{x \leftarrow E\}+E_{2}\{x \leftarrow E\} \\
E^{\prime}[X \leftarrow Y]\{x \leftarrow E\} & =E^{\prime}\{x \leftarrow E\}[X \leftarrow Y] \\
E^{\prime} \backslash X\{x \leftarrow E\} & =E^{\prime}\{x \leftarrow E\} \backslash X \\
E^{\prime}!X\{x \leftarrow E\} & =E^{\prime}\{x \leftarrow E\}!X \\
E^{\prime} . X\{x \leftarrow E\} & =E^{\prime}\{x \leftarrow E\} \cdot X \\
\text { close }\left(E^{\prime}\right)\{x \leftarrow E\} & =\operatorname{close}\left(E^{\prime}\{x \leftarrow E\}\right)
\end{aligned}
$$

Fig. 2. Operations on $C M S_{v}$ terms

$$
\begin{gathered}
\frac{y \notin F V(C)}{\lambda x \cdot C \equiv \lambda y \cdot C\{x \leftarrow y\}} \text { (core-alpha) } \\
\frac{y \notin F V(o) \cup \operatorname{dom}(\iota)}{\langle\iota+\{x \mapsto X\} ; o\rangle \equiv\langle\iota+\{y \mapsto X\} ; o\{x \leftarrow y\}\rangle} \text { (mixin-alpha) }
\end{gathered}
$$

Fig. 3. Structural equivalence between $C M S_{v}$ terms
assignment $o$. The input assignment associates internal variables to names of imported components, while the output assignment associates expressions to names of exported components. These expressions can refer to imported components via their associated internal variables. This explicit distinction between names and internal variables allows internal variables to be renamed by $\alpha$-conversion, while external names remain immutable, thus making projection by name unambiguous [Lillibridge 1997; Ancona and Zucca 1999; Wells and Vestergaard 2000].
The notation $x_{i} \stackrel{i \in I}{\mapsto} X_{i}$ denotes the finite map $\iota$ such that $\operatorname{dom}(\iota)=\left\{x_{i} \mid i \in I\right\}$ and for all $i \in I, \iota\left(x_{i}\right)=X_{i}$. It is valid only if for all $i, j \in I$, if $i \neq j$, then $x_{i} \neq x_{j}$. Then, $\operatorname{cod}(\iota)$ is $\left\{X_{i} \mid i \in I\right\}$. The finite maps $X_{i} \stackrel{i \in I}{\mapsto} E_{i}$ and $X_{i} \stackrel{i \in I}{\mapsto} \mathcal{T}_{i}$ are defined similarly.

The notions of free and bound variables, and of substitution are standard; they are defined in Figure 2.

Terms are identified up to structural equivalence, as defined in Figure 3. The equivalence rule (core-alpha) is standard $\alpha$-conversion on $\lambda$-bound variables. Rule (mixin-alpha) expresses that variables bound by the input assignment of a mixin structure can be renamed if no capture occurs. In this rule, we write $\iota_{1}+\iota_{2}$ for
the unique finite map $\iota$ such that for all $x \in \operatorname{dom}\left(\iota_{1}\right), \iota(x)=\iota_{1}(x)$ and for all $x \in \operatorname{dom}\left(\iota_{2}\right), \iota(x)=\iota_{2}(x)$. This map is defined only if $\iota_{1}(x)=\iota_{2}(x)$ for all $x \in \operatorname{dom}\left(\iota_{1}\right) \cap \operatorname{dom}\left(\iota_{2}\right)$.

Due to late binding, a virtual (defined but not frozen) component of a mixin is both imported and exported by the mixin: it is exported with its current definition, but is also imported so that other exported components refer to its final value at the time the component is frozen or the mixin is closed, rather than to its current value. In other terms, a component $X$ of $\langle\iota ; o\rangle$ is deferred when $X \in \operatorname{cod}(\iota) \backslash \operatorname{dom}(o)$, virtual when $X \in \operatorname{cod}(\iota) \cap \operatorname{dom}(o)$, and frozen when $X \in \operatorname{dom}(o) \backslash \operatorname{cod}(\iota)$.

For example, consider the following mixin, expressed in the ML-like syntax of section 2 :

$$
\operatorname{mix} ? v a l x: \text { int let } y=x+2 \text { let } z=y+1 \text { end }
$$

It is expressed in $C M S_{v}$ syntax as the structure $\langle\iota ; o\rangle$, where

$$
\begin{aligned}
\iota & =[x \mapsto X ; y \mapsto Y ; z \mapsto Z] \\
o & =[Y \mapsto x+2 ; Z \mapsto y+1] .
\end{aligned}
$$

The names $X, Y, Z$ correspond to the variables in the ML-like syntax, while the variables $x, y, z$ bind them locally. Here, $X$ is only an input, but $Y$ and $Z$ are both inputs and outputs, since these components are virtual. The definition of $Z$ refers to the imported value of $Y$, thus allowing later redefinition of $Y$ to affect $Z$.

### 3.2 Types and dependency graphs

Types $\mathcal{T}$ are either core types (those of the simply-typed $\lambda$-calculus) or mixin signatures $\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\}$. The latter are composed of two mappings $\mathcal{I}$ and $\mathcal{O}$ from names to types, one for input components, the other for output components, and a safe dependency graph $\mathcal{D}$.

A dependency graph $\mathcal{D}$ is a directed multi-graph whose nodes are external names of imported or exported components, and whose edges carry a valuation $\chi \in\{0,1\}$. An edge $X \xrightarrow{1} Y$ means that the term $E$ defining $Y$ refers to the value of $X$, but in such a way that it is safe to put $E$ in a recursive definition that simultaneously defines $X$ in terms of $Y$. An edge $X \xrightarrow{0} Y$ means that the term $E$ defining $Y$ cannot be put in such a recursive definition: the value of $X$ must be entirely computed before $E$ is evaluated. It is generally undecidable whether a dependency is of the 0 or 1 kind, so we take the following conservative approximation: if $E$ is an abstraction $\lambda x . C$, then all dependencies for $Y$ are labeled 1; in all other cases, they are all labeled 0 . (Other, more precise approximations are possible, but this one works well enough and is consistent with core ML.)
More formally, for $x \in F V(E)$, we define $\nu(x, E)=1$ if $E=\lambda y . C$ and $\nu(x, E)=$ 0 otherwise. Given the mixin structure $s=\langle\iota ; o\rangle$, we then define its dependency graph $\mathcal{D}(s)$ as follows: its nodes are the names of all components of $s$, and it contains an edge $X \xrightarrow{\chi} Y$ if and only if there exist $E$ and $x$ such that $o(Y)=E$ and $\iota(x)=X$ and $x \in F V(E)$ and $\chi=\nu(x, E)$. We then say that a dependency graph $\mathcal{D}$ is safe, and write $\vdash \mathcal{D}$, if all cycles of $\mathcal{D}$ are composed of edges labeled 1. This captures the idea that only dependencies of the " 1 " kind are allowed inside a mutually recursive definition.

In order to type-check mixin operators, we must be able to compute the dependency graph for the result of the operator given the dependency graphs for its operands. We now define the graph-level operators corresponding to the mixin operators.
Sum: the sum $\mathcal{D}_{1}+\mathcal{D}_{2}$ of two dependency graphs is simply their union:

$$
\mathcal{D}_{1}+\mathcal{D}_{2}=\left\{X \xrightarrow{\chi} Y \mid(X \xrightarrow{\chi} Y) \in \mathcal{D}_{1} \text { or }(X \xrightarrow{\chi} Y) \in \mathcal{D}_{2}\right\} .
$$

Rename: assuming $Y$ is not mentioned in $\mathcal{D}$, the graph $\mathcal{D}[X \leftarrow Y]$ is the graph $\mathcal{D}$ where the node $X$, if any, is renamed $Y$, keeping all edges unchanged.

$$
\mathcal{D}[X \leftarrow Y]=\{A\{X \leftarrow Y\} \xrightarrow{\chi} B\{X \leftarrow Y\} \mid(A \xrightarrow{\chi} B) \in \mathcal{D}\} .
$$

Delete: the graph $\mathcal{D} \backslash X$ is the graph $\mathcal{D}$ where we remove all edges leading to $X$.

$$
\mathcal{D} \backslash X=\mathcal{D} \backslash\{Y \xrightarrow{\chi} X \mid Y \in \text { Names, } \chi \in\{0,1\}\} .
$$

Freeze: operationally, the effect of freezing the component $X$ in a mixin structure is to replace $X$ by its current definition $E$ in all definitions of other exported components. At the dependency level, this causes all components $Y$ that previously depended on $X$ to now depend on the names on which $E$ depends. Thus, paths $Y \xrightarrow{\chi_{1}} X \xrightarrow{\chi_{2}} Z$ in the original graph become edges $Y \xrightarrow{\min \left(\chi_{1}, \chi_{2}\right)} Z$ in the result graph.

$$
\begin{aligned}
& \mathcal{D}!X=\left(\mathcal{D} \cup \mathcal{D}_{\text {around }}\right) \backslash \mathcal{D}_{\text {remove }} \\
& \text { where } \mathcal{D}_{\text {around }}=\left\{Y \xrightarrow{\min \left(\chi_{1}, \chi_{2}\right)} Z \mid\left(Y \xrightarrow{\chi_{1}} X\right) \in \mathcal{D},\left(X \xrightarrow{\chi_{2}} Z\right) \in \mathcal{D}\right\} \\
& \text { and } \quad \mathcal{D}_{\text {remove }}=\{X \xrightarrow{\chi} Y \mid Y \in \text { Names, } \chi \in\{0,1\}\} \text {. }
\end{aligned}
$$

The sum of two safe graphs is not necessarily safe (unsafe cycles may appear); thus, the typing rules explicitly check the safety of the sum. Remarkably, all other graph operations preserve safety.

Lemma 3.1. If $\mathcal{D}$ is a safe dependency graph, then the graphs $\mathcal{D}[X \leftarrow Y], \mathcal{D} \backslash X$ and $\mathcal{D}!X$ are safe.
The proof is given in appendix A.

### 3.3 Typing rules

The typing rules for $C M S_{v}$ are shown in Figure 4. The typing environment $\Gamma$ is a finite map from variables to types. We assume given a mapping $T C$ from constants to core types. All dependency graphs appearing in the typing environment and in input signatures are assumed to be safe.

The rules resemble those of Ancona and Zucca [2002], with additional manipulations of dependency graphs. Projection of a structure component requires that the structure has no input components. Structure construction type-checks every output component in an environment enriched with the types assigned to the input components; it also checks that the corresponding dependency graph is safe. For the sum operator, both mixins must agree on the types of common input components, and must have no output components in common; again, we need to check that the dependency graph of the sum is safe, to make sure that the sum introduces no illegal recursive definitions. Freezing a component requires that its type in the input

$$
\begin{aligned}
& \Gamma \vdash x: \Gamma(x) \text { (var) } \quad \Gamma \vdash c: T C(c) \text { (const) } \quad \frac{\Gamma+\left\{x: \tau_{1}\right\} \vdash C: \tau_{2}}{\Gamma \vdash \lambda x . C: \tau_{1} \rightarrow \tau_{2}} \text { (abstr) } \\
& \frac{\Gamma \vdash C_{1}: \tau^{\prime} \rightarrow \tau \quad \Gamma \vdash C_{2}: \tau^{\prime}}{\Gamma \vdash C_{1} C_{2}: \tau}(\mathrm{app}) \quad \frac{\Gamma \vdash E:\{\emptyset ; \mathcal{O} ; \emptyset\}}{\Gamma \vdash E . X: \mathcal{O}(X)} \text { (select) } \\
& \vdash \mathcal{D}\langle\iota ; o\rangle \quad \operatorname{dom}(o)=\operatorname{dom}(\mathcal{O}) \\
& \frac{\Gamma+\{x: \mathcal{I}(\iota(x)) \mid x \in \operatorname{dom}(\iota)\} \vdash o(X): \mathcal{O}(X) \text { for } X \in \operatorname{dom}(o)}{\Gamma \vdash\langle\iota ; o\rangle:\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\langle\iota ; o\rangle\}} \text { (struct) } \\
& \Gamma \vdash E_{1}:\left\{\mathcal{I}_{1} ; \mathcal{O}_{1} ; \mathcal{D}_{1}\right\} \quad \Gamma \vdash E_{2}:\left\{\mathcal{I}_{2} ; \mathcal{O}_{2} ; \mathcal{D}_{2}\right\} \quad \vdash \mathcal{D}_{1}+\mathcal{D}_{2} \\
& \underline{\operatorname{dom}\left(\mathcal{O}_{1}\right) \cap \operatorname{dom}\left(\mathcal{O}_{2}\right)=\emptyset \quad \mathcal{I}_{1}(X)=\mathcal{I}_{2}(X) \text { for all } X \in \operatorname{dom}\left(\mathcal{I}_{1}\right) \cap \operatorname{dom}\left(\mathcal{I}_{2}\right)} \text { (sum) } \\
& \Gamma \vdash E_{1}+E_{2}:\left\{\mathcal{I}_{1}+\mathcal{I}_{2} ; \mathcal{O}_{1}+\mathcal{O}_{2} ; \mathcal{D}_{1}+\mathcal{D}_{2}\right\} \\
& \frac{\Gamma \vdash E:\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\} \quad \mathcal{I}(X)=\mathcal{O}(X)}{\Gamma \vdash E!X:\left\{\mathcal{I}_{\backslash X} ; \mathcal{O} ; \mathcal{D}!X\right\}} \text { (freeze) } \quad \frac{\Gamma \vdash E:\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\} \quad X \in \operatorname{dom}(\mathcal{O})}{\Gamma \vdash E \backslash X:\{\mathcal{I} ; \mathcal{O} \backslash X ; \mathcal{D} \backslash X\}} \text { (delete) } \\
& \frac{\Gamma \vdash E:\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\} \quad Y \notin \operatorname{dom}(\mathcal{I}) \cup \operatorname{dom}(\mathcal{O})}{\Gamma \vdash E[X \leftarrow Y]:\{\mathcal{I} \circ[Y \mapsto X] ; \mathcal{O} \circ[Y \mapsto X] ; \mathcal{D}[X \leftarrow Y]\}} \text { (rename) } \\
& \frac{\Gamma \vdash E:\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\} \quad \operatorname{dom}(\mathcal{I}) \subseteq \operatorname{dom}(\mathcal{O}) \quad \mathcal{I}(X)=\mathcal{O}(X) \text { for all } X \in \operatorname{dom}(\mathcal{I})}{\Gamma \vdash \operatorname{close}(E):\{\emptyset ; \mathcal{O} ; \emptyset\}} \text { (close) } \\
& \Gamma \vdash \operatorname{close}(E):\{\emptyset ; \mathcal{O} ; \emptyset\}
\end{aligned}
$$

Fig. 4. Typing rules for $C M S_{v}$
signature and in the output signature of the structure are identical, then removes it from the input signature. (The notation $\mathcal{I}_{\backslash X}$ denotes the finite map obtained from $\mathcal{I}$ by removing the binding for $X$.) In contrast, deleting a component removes it from the output signature. Finally, closing a mixin is equivalent to freezing all its input components, and results in an empty input signature and dependency graph.

Continuing the example at the end of section 3.1, the mixin $\langle\iota ; o\rangle$, where $\iota=$ $[x \mapsto X ; y \mapsto Y ; z \mapsto Z]$ and $o=[Y \mapsto x+2 ; Z \mapsto y+1]$, has type $\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\}$, where

$$
\begin{aligned}
\mathcal{I} & =[X \mapsto \text { int } ; Y \mapsto \text { int } ; Z \mapsto \text { int }] \\
\mathcal{O} & =[Y \mapsto \text { int } ; Z \mapsto \text { int }] \\
\mathcal{D} & =X \xrightarrow{0} Y \xrightarrow{0} Z .
\end{aligned}
$$

For simplicity, the rules (sum), (freeze) and (close) require strict syntactic equality of types. Although we will not do it here, it is possible to introduce a notion of subtyping [Ancona and Zucca 2002] corresponding to adding input components, removing output components, and adding "fake" dependencies in dependency graphs.

Our goal is to translate well-typed terms of $C M S_{v}$ into a simple calculus with let rec, relying on the dependency graphs. To do this in a sound way, it is crucial to only have to deal with safe dependency graphs. For this purpose, we define the notion of a well-formed type, as described in Figure 5. A core type is always well-formed, whereas a mixin type $\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\}$ is well-formed if $\mathcal{D}$ as well as the graphs appearing in $\mathcal{I}$ and $\mathcal{O}$ are safe, and moreover $\operatorname{Sources}(\mathcal{D})$ and $\operatorname{Sinks}(\mathcal{D})$, the set of nodes possessing at least one outgoing (respectively, incoming) edge, are
$\operatorname{Sources}(\mathcal{D}) \subset \operatorname{dom}(\mathcal{I}) \quad \operatorname{Sinks}(\mathcal{D}) \subset \operatorname{dom}(\mathcal{O})$
$\vdash \tau$ (core) $\frac{\vdash \mathcal{I}(X) \text { for all } X \in \operatorname{dom}(\mathcal{I}) \quad \vdash \mathcal{O}(X) \text { for all } X \in \operatorname{dom}(\mathcal{O}) \quad \vdash \mathcal{D}}{\vdash\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\}}$ (mixin)

Fig. 5. Well-formed $C M S_{v}$ types
included in $\operatorname{dom}(\mathcal{I})$ (respectively, $\operatorname{dom}(\mathcal{O})$ ). Our type system satisfies the following well-formedness property.

Lemma 3.2. If $\Gamma \vdash E: \mathcal{T}$ is derivable, and $\vdash \Gamma(x)$ for all $x \in \operatorname{dom}(\Gamma)$, then $\vdash \mathcal{T}$.
Proof. The proof is a simple induction on the proof tree, relying on the condition that all the dependency graphs appearing in the environment and in input signatures are safe, on lemma A.1, and on the safety checks in the rules (sum) and (struct).

## 4. COMPILATION

We now present a compilation scheme translating $C M S_{v}$ terms into call-by-value $\lambda$-calculus extended with records and a let rec binding. This compilation scheme is compositional and type-directed, thus supporting separate compilation.

### 4.1 Overview

A mixin structure is translated into a record with one field per output component of the structure. Each field corresponds to the expression defining the output component, but $\lambda$-abstracts all input components on which it depends, that is, all its direct predecessors in the dependency graph. These extra parameters account for the late binding semantics of virtual components. Consider again the M1 and M2 example at the end of section 2. These two structures are translated to:

```
m1 = {f=\lambdag.\lambdax. ...g...; u = \lambdaf. f 0 }
m2 = {g = \lambdaf.\lambdax. ...f...; v = \lambdag. g 1 }
```

The sum $\mathrm{M}=\mathrm{M} 1+\mathrm{M} 2$ is then translated into a record that takes the union of the two records m 1 and m 2 :

```
m = { f = m1.f; u = m1.u; g = m2.g; v = m2.v }
```

Later, we close M. This requires connecting the formal parameters representing input components with the record fields corresponding to the output components. To do this, we examine the dependency graph of M , identifying the strongly connected components and performing a topological sort. We thus see that we must first take a fixpoint over the $f$ and $g$ components, then compute $u$ and $v$ sequentially. Thus, we obtain the following code for close(M):

```
let rec f = m.f g and g = m.g f in
let u = m.u f in
let v = m.v g in
{f=f;g=g;u = u; v = v }
```

Notice that the let rec definition we generate is unusual: it involves function applications in the right-hand sides, which is usually not supported in call-by-value

## Values

$$
v::=x|\lambda x . M|\left\langle\ldots X_{i}=v_{i} \ldots\right\rangle \mid c
$$

## Evaluation contexts

$$
\begin{aligned}
\mathbb{E}::= & {[] M|v[]|[] . X } \\
& \mid \text { let rec } \ldots x_{i-1}=v_{i-1} \text { and } x_{i}=[] \text { and } \ldots x_{n}=M_{n} \text { in } M \\
& \mid \text { let } x=[] \text { in } M \\
& \left\langle\ldots ; X_{i-1}=v_{i-1} ; X_{i}=[] ; X_{i+1}=M_{i+1} ; \ldots\right\rangle
\end{aligned}
$$

Parallel substitution by $\rho=\ldots x_{i} \leftarrow M_{i} \ldots$

$$
\begin{array}{rlrl}
x\{\rho\} & =M_{i} & \text { if } x=x_{i} \\
x\{\rho\} & =x & & \text { otherwise } \\
(\lambda x \cdot M)\{\rho\} & =\lambda x .(M\{\rho\}) & & \text { if } x \notin \bigcup_{i}\left(\left\{x_{i}\right\} \cup F V\left(M_{i}\right)\right) \\
\left(M_{1} M_{2}\right)\{\rho\} & =M_{1}\{\rho\} M_{2}\{\rho\} & \\
\left(\text { let rec } \ldots y_{k}=N_{k} \ldots \text { in } M\right)\{\rho\} & = & \text { let rec } \ldots y_{k}=N_{k}\{\rho\} \ldots \text { in } M\{\rho\} \\
& & \text { if }\left(\bigcup_{k}\left\{y_{k}\right\}\right) \cap \bigcup_{i}\left(\left\{x_{i}\right\} \cup F V\left(M_{i}\right)\right) \neq \emptyset \\
\left\langle\ldots X_{i}=M_{i} \ldots\right\rangle\{\rho\} & =\left\langle\ldots X_{i}=M_{i}\{\rho\} \ldots\right\rangle
\end{array}
$$

## Reduction rules

$$
\begin{aligned}
(\lambda x \cdot M) v & \rightarrow M\{x \leftarrow v\} & \text { (beta) } \\
\text { let } x=v \text { in } M & \rightarrow M\{x \leftarrow v\} & \text { (bind) } \\
\left\langle X_{1}=v_{1} \ldots X_{n}=v_{n}\right\rangle \cdot X_{i} & \rightarrow v_{i} & \text { (select) } \\
\text { let rec } x_{1}=v_{1} \ldots x_{n}=v_{n} \text { in } M & \rightarrow M\left\{x_{1} \leftarrow M_{1} \ldots x_{n} \leftarrow M_{n}\right\} & \text { (mutrec) }
\end{aligned}
$$

where $M_{j}=$ let rec $x_{1}=v_{1} \ldots x_{n}=v_{n}$ in $v_{j}$ for $j=1, \ldots, n$.

$$
\frac{M \rightarrow M^{\prime}}{\mathbb{E}[M] \rightarrow \mathbb{E}\left[M^{\prime}\right]} \text { (context) }
$$

Fig. 6. Dynamic semantics of $\lambda_{B}$
$\lambda$-calculi. Fortunately, Boudol [2003] has already developed a non-standard call-by-value calculus that supports such let rec definitions; we adopt a variant of his calculus as our target language.

### 4.2 The target language

The target language for our translation is the $\lambda_{B}$ calculus, a variant of the $\lambda$-calculus with records and recursive definitions introduced by Boudol [2003]. Its syntax is as follows:

$$
\begin{aligned}
M::= & x \mid \text { cst }|\lambda x . M| M_{1} M_{2} \\
& \left|\left\langle X_{1}=M_{1} ; \ldots ; X_{n}=M_{n}\right\rangle\right| M . X \\
& \mid \text { let } x=M_{1} \text { in } M \\
& \mid \text { let rec } x_{1}=M_{1} \text { and } \ldots \text { and } x_{n}=M_{n} \text { in } M
\end{aligned}
$$

Compared with Boudol's calculus, ours lacks references and extensible records, but features mutual recursion. The dynamic semantics of this calculus is given by Boudol's reduction rules [Boudol 2003]. Although they implement a call-by-value strategy, these rules are able to evaluate correctly recursive definitions involving

```
\(\llbracket\left(E: \mathcal{T}^{\prime}\right) \cdot X: \mathcal{T} \rrbracket=\llbracket E: \mathcal{T}^{\prime} \rrbracket \cdot X\)
\(\llbracket\langle\langle; o\rangle:\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\} \rrbracket=\)
    \(\left\langle X=\vec{\lambda}_{\iota}^{-1}\left(\mathcal{D}^{-1}(X)\right) . \llbracket o(X): \mathcal{O}(X) \rrbracket \mid X \in \operatorname{dom}(\mathcal{O})\right\rangle\)
\(\llbracket\left(E_{1}:\left\{\mathcal{I}_{1} ; \mathcal{O}_{1} ; \mathcal{D}_{1}\right\}\right)+\left(E_{2}:\left\{\mathcal{I}_{2} ; \mathcal{O}_{2} ; \mathcal{D}_{2}\right\}\right):\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\} \rrbracket=\)
    let \(e_{1}=\llbracket E_{1}:\left\{\mathcal{I}_{1} ; \mathcal{O}_{1} ; \mathcal{D}_{1}\right\} \rrbracket\) in let \(e_{2}=\llbracket E_{2}:\left\{\mathcal{I}_{2} ; \mathcal{O}_{2} ; \mathcal{D}_{2}\right\} \rrbracket\) in
    \(\left\langle X=e_{1} \cdot X\right| X \in \operatorname{dom}\left(\mathcal{O}_{1}\right)\);
    \(Y=e_{2} . Y\left|Y \in \operatorname{dom}\left(\mathcal{O}_{2}\right)\right\rangle\)
\(\llbracket\left(E:\left\{\mathcal{I}^{\prime} ; \mathcal{O}^{\prime} ; \mathcal{D}^{\prime}\right\}\right) \backslash X:\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\} \rrbracket=\)
    let \(e=\llbracket E:\left\{\mathcal{I}^{\prime} ; \mathcal{O}^{\prime} ; \mathcal{D}^{\prime}\right\} \rrbracket\) in \(\langle Y=e . Y \mid Y \in \operatorname{dom}(\mathcal{O})\rangle\)
\(\llbracket\left(E:\left\{\mathcal{I}^{\prime} ; \mathcal{O}^{\prime} ; \mathcal{D}^{\prime}\right\}\right)[X \leftarrow Y]:\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\} \rrbracket=\)
    let \(e=\llbracket E:\left\{\mathcal{I}^{\prime} ; \mathcal{O}^{\prime} ; \mathcal{D}^{\prime}\right\} \rrbracket\) in
    \(\left\langle Z\{X \leftarrow Y\}=\vec{\lambda} \overline{\mathcal{D}^{-1}(Z\{X \leftarrow Y\})} .\left(e . Z \overline{\mathcal{D}^{\prime-1}(Z)}\right)\{\bar{X} \leftarrow \bar{Y}\} \mid Z \in \operatorname{dom}\left(\mathcal{O}^{\prime}\right)\right\rangle\)
\(\llbracket\left(E:\left\{\mathcal{I}^{\prime} ; \mathcal{O}^{\prime} ; \mathcal{D}^{\prime}\right\}\right)!X:\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\} \rrbracket=\)
    let \(e=\llbracket E:\left\{\mathcal{I}^{\prime} ; \mathcal{O}^{\prime} ; \mathcal{D}^{\prime}\right\} \rrbracket\) in
    \(\langle Z=e . Z| Z \in \operatorname{dom}(\mathcal{O}), X \notin \mathcal{D}^{\prime-1}(Z)\);
    \(Y=\vec{\lambda} \overline{\mathcal{D}^{-1}(Y)}\). let rec \(\bar{X}=e . X \overline{\mathcal{D}^{\prime-1}(X)}\) in \(e . Y \overline{\mathcal{D}^{\prime-1}(Y)}\left|X \in \mathcal{D}^{\prime-1}(Y)\right\rangle\)
\(\llbracket c \operatorname{cose}\left(E:\left\{\mathcal{I}^{\prime} ; \mathcal{O}^{\prime} ; \mathcal{D}^{\prime}\right\}\right):\{\emptyset ; \mathcal{O} ; \emptyset\} \rrbracket=\)
    let \(e=\llbracket E:\left\{\mathcal{I}^{\prime} ; \mathcal{O}^{\prime} ; \mathcal{D}^{\prime}\right\} \rrbracket\) in
    let rec \(\overline{X_{1}^{1}}=e . X_{1}^{1} \overline{\mathcal{D}^{\prime-1}\left(X_{1}^{1}\right)}\) and \(\ldots\) and \(\overline{X_{n_{1}}^{1}}=e . X_{n_{1}}^{1} \overline{\mathcal{D}^{\prime-1}\left(X_{n_{1}}^{1}\right)}\) in
    let rec \(\overline{X_{1}^{p}}=e . X_{1}^{p} \overline{\mathcal{D}^{\prime-1}\left(X_{1}^{p}\right)}\) and \(\ldots\) and \(\overline{X_{n_{p}}^{p}}=e . X_{n_{p}}^{p} \overline{\mathcal{D}^{\prime-1}\left(X_{n_{p}}^{p}\right)}\) in
    \(\langle X=\bar{X} \mid X \in \operatorname{dom}(\mathcal{O})\rangle\)
    where \(\left(\left\{X_{1}^{1} \ldots X_{n_{1}}^{1}\right\}, \ldots,\left\{X_{1}^{p} \ldots X_{n_{p}}^{p}\right\}\right)\) is a serialization of \(\operatorname{dom}\left(\mathcal{O}^{\prime}\right)\) against \(\mathcal{D}^{\prime}\)
```

Fig. 7. The translation scheme from $C M S_{v}$ to $\lambda_{B}$
function applications, such as:

$$
\text { let rec } \begin{aligned}
x=(\lambda y z \cdot(z y)) x \text { in } x & \rightarrow \text { let rec } x=\lambda z \cdot(z x) \text { in } x \\
& \rightarrow \text { let rec } x=\lambda z \cdot(z x) \text { in } \lambda z \cdot(z x) \\
& \rightarrow \lambda z \cdot(z(\text { let rec } x=\lambda z \cdot(z x) \text { in } \lambda z \cdot(z x))) .
\end{aligned}
$$

The dynamic semantics of the calculus is defined in Figure 6. The only difference from standard call-by-value evaluation is that variables are considered values. Thus, applications such as $(\lambda y z .(z y)) x$ are redexes, and recursive definitions such as the one above can be reduced. Notice that the (mutrec) rule crucially relies on parallel capture-avoiding substitution, also defined in Figure 6.

### 4.3 The translation

The translation scheme for our language is defined in Figure 7. The translation, written $\llbracket E: \mathcal{T} \rrbracket$ is type-directed and operates on terms $E$ annotated by their types $\mathcal{T}$. For the core language constructs (variables, constants, abstractions, applications), the translation is a simple morphism; the corresponding cases are omitted from Figure 7.

Access to a structure component E.X is translated into an access to field $X$ of the
record obtained by translating $E$. Conversely, a structure $\langle\iota ; o\rangle$ is translated into a record construction. The resulting record has one field for each exported name $X \in \operatorname{dom}(o)$, and this field is associated with $o(X)$ where all input parameters on which $X$ depends are $\lambda$-abstracted. Some notation is required here. We write $\mathcal{D}^{-1}(X)$ for the list of immediate predecessors of node $X$ in the dependency graph $\mathcal{D}$, ordered lexicographically. (The ordering is needed to ensure that values for these predecessors are provided in the correct order later; any fixed total ordering will do.) If $\left(X_{1}, \ldots, X_{n}\right)=\mathcal{D}^{-1}(X)$ is such a list, we write $\iota^{-1}\left(\mathcal{D}^{-1}(X)\right)$ for the list $\left(x_{1}, \ldots, x_{n}\right)$ of variables associated to the names $\left(X_{1}, \ldots, X_{n}\right)$ by the input mapping $\iota$. Finally, we write $\vec{\lambda}\left(x_{1}, \ldots, x_{n}\right) \cdot M$ as shorthand for $\lambda x_{1} \ldots \lambda x_{n} \cdot M$. With all this notation, the field $X$ in the record translating $\langle\iota ; o\rangle$ is bound to $\vec{\lambda}_{\iota}{ }^{-1}\left(\mathcal{D}^{-1}(X)\right) . \llbracket o(X): \mathcal{O}(X) \rrbracket$.

The sum of two mixins $E_{1}+E_{2}$ is translated by building a record containing the union of the fields of the translations of $E_{1}$ and $E_{2}$. For the delete operator $E \backslash X$, we return a copy of the record representing $E$ in which the field $X$ is omitted. Renaming $E[X \leftarrow Y]$ is harder: not only do we need to rename the field $X$ of the record representing $E$ into $Y$, but the renaming of $X$ to $Y$ in the input parameters can cause the order of the implicit arguments of the record fields to change. Thus, we need to abstract again over these parameters in the correct order after the renaming, then apply the corresponding field of $\llbracket E \rrbracket$ to these parameters in the correct order before the renaming. Again, some notation is in order: to each name $X$ we associate a fresh variable written $\bar{X}$, and similarly for lists of names, which become lists of variables. Moreover, we write $M\left(x_{1}, \ldots, x_{n}\right)$ as shorthand for $M x_{1} \ldots x_{n}$.

The freeze operation $E!X$ is perhaps the hardest to compile. Output components $Z$ that do not depend on $X$ are simply re-exported from $\llbracket E \rrbracket$. For the other output components, consider a component $Y$ of $E$ that depends on $Y_{1}, \ldots, Y_{n}$, and assume that one of these dependencies is $X$, which itself depends on $X_{1}, \ldots, X_{p}$. In $E!X$, the $Y$ component depends on $\left\{Y_{1} \ldots Y_{n}, X_{1} \ldots X_{p}\right\} \backslash\{X\}$. Thus, we $\lambda$ abstract on the corresponding variables, then compute $X$ by applying $\llbracket E \rrbracket \cdot X$ to the parameters $\overline{X_{j}}$. Since $X$ can depend on itself, this application must be done in a let rec binding over $\bar{X}$. Then, we apply $\llbracket E \rrbracket . Y$ to the parameters that it expects, namely $\overline{Y_{i}}$, which include $\bar{X}$.

The only operator that remains to be explained is close $(E)$. Here, we take advantage of the fact that close removes all input dependencies to generate code that is more efficient than a sequence of freeze operations. We first serialize the set of names exported by $E$ against its dependency graph $\mathcal{D}$. That is, we identify strongly connected components of $\mathcal{D}$, then sort them in topological order. The result is an enumeration $\left(\left\{X_{1}^{1} \ldots X_{n_{1}}^{1}\right\}, \ldots,\left\{X_{1}^{p} \ldots X_{n_{p}}^{p}\right\}\right)$ of the exported names where each cluster $\left\{X_{1}^{i} \ldots X_{n_{i}}^{i}\right\}$ represents mutually recursive definitions, and the clusters are listed in an order such that each cluster depends only on the preceding ones. We then generate a sequence of let rec bindings, one for each cluster, in the order above. In the end, all output components are bound to values with no dependencies, and can be grouped together in a record.

$$
\begin{aligned}
& \frac{\gamma(x)=0}{\Gamma \vdash x: \Gamma(x) / \gamma}(\mathrm{var}) \quad \Gamma \vdash c: T C(c) / \gamma \text { (const) } \\
& \frac{\Gamma+\left\{x: \tau^{\prime}\right\} \vdash M: \tau /(\gamma-1)[x \mapsto d]}{\Gamma \vdash \lambda x . M: \tau^{\prime} \xrightarrow{d} \tau / \gamma} \text { (abstr) } \\
& \frac{\Gamma \vdash M_{1}: \tau^{\prime} \xrightarrow{d} \tau / \gamma_{1} \quad \Gamma \vdash M_{2}: \tau^{\prime} / \gamma_{2}}{\Gamma \vdash M_{1} M_{2}: \tau /\left(\gamma_{1}-1\right) \wedge d @ \gamma_{2}}(\operatorname{app}) \\
& \frac{\Gamma \vdash M: \tau^{\prime} \xrightarrow{d} \tau / \gamma \quad \Gamma(x)=\tau^{\prime}}{\Gamma \vdash M x: \tau /(\gamma-1) \wedge(x \mapsto d)} \text { (appvar) } \\
& \frac{\Gamma \vdash M: \tau^{\prime} / \gamma^{\prime} \quad \Gamma+\left\{x: \tau^{\prime}\right\} \vdash N: \tau / \gamma[x \mapsto d]}{\Gamma \vdash \operatorname{let} x=M \operatorname{in} N: \tau / \gamma \wedge d @ \gamma^{\prime}} \text { (let) } \\
& \Gamma+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash M: \tau / \gamma\left[\ldots x_{j} \mapsto d_{j} \ldots\right] \\
& \forall i: \Gamma+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash M_{i}: \tau_{i} / \gamma_{i}\left[\ldots x_{j} \mapsto d_{i j} \ldots\right] \\
& \forall i, j: d_{i j} \geq 1 \quad \forall i, j, k: d_{i k} \leq d_{i j} @ d_{j k} \\
& \Gamma \vdash \text { let rec } \ldots x_{i}=M_{i} \ldots \text { in } M: \tau / \gamma \wedge\left(\bigwedge_{i} d_{i} @ \gamma_{i}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ \gamma_{j}\right) \\
& \frac{\forall i: \Gamma \vdash M_{i}: \tau_{i} / \gamma}{\Gamma \vdash\left\langle\ldots X_{i}=M_{i} \ldots\right\rangle:\left\langle\ldots X_{i}: \tau_{i} \ldots\right\rangle / \gamma} \text { (record) } \\
& \frac{\Gamma \vdash M:\left\langle\ldots X_{j}: \tau_{j} \ldots\right\rangle / \gamma \quad 1 \leq i \leq n}{\Gamma \vdash M \cdot X_{i}: \tau_{i} / \gamma}(\mathrm{sel})
\end{aligned}
$$

Fig. 8. Typing rules for $\lambda_{B}$

## 5. TYPE SOUNDNESS OF THE TRANSLATION

### 5.1 A type system for the target language

The translation scheme defined above can generate recursive definitions of the form let rec $x=M x$ in $N$. In $\lambda_{B}$, these definitions can either evaluate to a fixpoint (for instance, $M=\lambda x . \lambda y . y$ ), or get stuck (for instance, $M=\lambda x . x(\lambda y . y)$ ). In preparation for showing that no term generated by the translation can get stuck, we now equip $\lambda_{B}$ with a sound type system that guarantees that all recursive definitions are correct. Boudol [2003] gave such a type system, using annotated function types $\tau_{1} \xrightarrow{0} \tau_{2}$ and $\tau_{1} \xrightarrow{1} \tau_{2}$ to distinguish functions that respectively need or do not need the value of their argument immediately after application. However, Boudol's type system does not keep track of dependencies in curried functions with sufficient precision for our purposes. Hence we now define a refinement of Boudol's type system, where the annotations 0 and 1 on function types are generalized into natural integers.

The type system for $\lambda_{B}$ is defined in Figure 8. Types, written $\tau$, have the following syntax:
$\begin{aligned} \lambda_{B} \text { types: } & \tau::=\text { int } \mid \text { bool } & & \text { base types } \\ & \mid \tau_{1} \xrightarrow{d} \tau_{2} & & \text { annotated function types }\end{aligned}$
ACM Transactions on Programming Languages and Systems, Vol. 27, No. 5, September 2005.

$$
\mid\left\langle\ldots X_{i}: \tau_{i} \ldots\right\rangle \text { record types }
$$

Arrow types are annotated with degrees $d$, indicating how a function uses its argument. For instance, a function such as $\lambda x \cdot x+1$ has type int $\xrightarrow{0}$ int, because the value of $x$ is immediately needed after application, whereas $\lambda x y z . x+1$ has type int $\xrightarrow{2} \ldots$ because the value of $x$ is not needed unless at least 2 more function applications are performed. Formally, a degree can be either a natural number or $\infty$, meaning that the variable is not used. The typing judgment is of the form $\Gamma \vdash M: \tau / \gamma$, where $\gamma$ is a (total) mapping from variables to degrees, indicating how $M$ uses each variable: $\gamma(x)=\infty$ means that $x$ is not free in $M ; \gamma(x)=0$ means that the value of $x$ may be needed to evaluate $M$; and $\gamma(x)=n+1$ means that the value of $x$ is definitely not needed when apply $M$ to $n$ or fewer function applications, for instance if $x$ occurs in $M$ under at least $n+1$ function abstractions.
Rule (var) expresses that the variable $x$ is immediately used via the side condition $\gamma(x)=0$. Function abstraction (rule (abstr)) increments by 1 the degree of all variables appearing in its body, except for its formal parameter $x$, whose degree is retained in the type of the function. We write $\gamma-1$ for the function $y \mapsto \gamma(y)-1$, with the convention that $0-1=0$ and $\infty-1=\infty$. We write $(\gamma-1)[x \mapsto d]$ for the function that maps $x$ to $d$, and otherwise behaves like $(\gamma-1)$.

Rule (app) deals with general function application. In the function part $M_{1}$, all variable degrees are decremented by 1 , since the application removes one level of abstraction. The degrees of the argument part $M_{2}$ are combined with the $d$ annotation on the arrow type of $M_{1}$ via the @ operation, defined as follows:

$$
d @ 0=0 \quad d @ \infty=\infty \quad d @(n+1)=d .
$$

Because of call-by-value, immediate dependencies in $M_{2}\left(\gamma_{2}(x)=0\right)$ are still immediate in the application. Variables not free in $M_{2}\left(\gamma_{2}(x)=\infty\right)$ do not contribute any dependency to the application. The interesting case is that of a variable $x$ with degree $n+1$ in $M_{2}$, i.e. not immediately needed. We do not know to how many arguments the function $M_{1}$ is going to apply its argument inside its body. However, we know that it will not do so before $d$ more applications of $M_{1} M_{2}$. Hence, we can take $d$ for the degree of $x$ in $M_{1} M_{2}$. Finally, the contributions from the function part $\left(\gamma_{1}-1\right)$ and the argument part $\left(d @ \gamma_{2}\right)$ are combined with the $\wedge$ operator, which is point-wise minimum.

When the argument of an application is a variable, as in $M x$, a more precise type-checking is possible (rule (appvar)). Namely, the variable $x$ is not needed immediately, but only when the function $M$ needs its argument. Hence, the degree of $x$ in the application is $(\gamma(x)-1) \wedge d$, while all other variables $y$ have degree $\gamma(y)-1$.

The most complex rule is (rec) for mutual recursive definitions. Intuitively, the right-hand sides $M_{1} \ldots M_{n}$ must not depend immediately on any of the recursively defined variables $x_{1} \ldots x_{n}$. In other terms, the dependency $d_{i j}$ of $M_{i}$ on $x_{j}$ must satisfy $d_{i j} \geq 1$. However, we must also take into account indirect dependencies: for instance, $M_{1}$ may depend on $x_{2}$, whose definition $M_{2}$ in turn depends on $x_{3}$, making $M_{1}$ depend on $x_{3}$ as well. We account for these indirect dependencies via the premises $d_{i k} \leq d_{i j} @ d_{j k}$, which we nickname the "triangular inequalities". Finally, the dependencies of the whole let rec are obtained by combining those of its body

```
\(\mathcal{D}^{-1}(X)=\left(X_{1}, \ldots, X_{n}\right)\) is the list of the predecessors of \(X\) in \(\mathcal{D}\), ordered lexicographically.
\(\mathcal{D}(X, Y)=\min \{\chi \mid X \xrightarrow{\chi} Y \in \mathcal{D}\}\) (with the convention that \(\mathcal{D}(X, Y)=\infty\) if \(D\) contains no
edges from \(X\) to \(Y\) )
\(F C T_{\mathcal{D}}(X, \mathcal{I})=\left(\mathcal{T}_{1}^{\chi_{1}}, \ldots, \mathcal{T}_{n}^{\chi_{n}}\right)\), for \(\operatorname{Sources}(\mathcal{D}) \subset \operatorname{dom}(\mathcal{I})\), where \(\mathcal{D}^{-1}(X)=\left(X_{1}, \ldots, X_{n}\right)\)
and for all \(i \in\{1 \ldots n\}, \mathcal{I}\left(X_{i}\right)=\mathcal{T}_{i}\) and \(\mathcal{D}\left(X_{i}, X\right)=\chi_{i}\).
Sources \((\mathcal{D})=\{X \mid X \xrightarrow{\chi} Y \in \mathcal{D}, X, Y \in\) Names, \(\chi \in\) Vals \(\}\)
\(\operatorname{Sinks}(\mathcal{D})=\{Y \mid X \xrightarrow{\chi} Y \in \mathcal{D}, X, Y \in\) Names, \(\chi \in\) Vals \(\}\)
```

Fig. 9. Operations on graphs
$M$ with those arising from the uses of the $x_{i}$ in $M$, either direct $\left(d_{i} @ \gamma_{i}\right)$ or one-step indirect ( $d_{i} @ d_{i j} @ \gamma_{j}$ ). Longer indirect dependencies such as $d_{i} @ d_{i j} @ d_{j k} @ \gamma_{k}$ need not be taken into account because of the triangular inequalities.

Finally, the (let) rule is a combination of the (abstr) and (app) rules, and the rules for record operations (record) and (sel) are straightforward.

Theorem 5.1. (Soundness of $\lambda_{B}$.) If $\Gamma \vdash M: \tau / \gamma$ and $\gamma(x) \geq 1$ for all $x$ free in $M$, then $M$ either reduces to a value or diverges, but does not get stuck.

Proof. The theorem follows from the following lemmas, which are proved in appendix B. The first three lemmas are substitution lemmas for general one-variable substitution, substitution of one variable by another, and parallel substitution. They play a crucial role for proving subject reduction for the typing rules (app), (appvar) and (rec) respectively.

Lemma 5.2. (Substitution.) If $\Gamma+\left\{x \mapsto \tau^{\prime}\right\} \vdash M_{1}: \tau / \gamma_{1}[x \mapsto d]$, and $\Gamma \vdash M_{2}$ : $\tau^{\prime} / \gamma_{2}$, with $x \notin F V\left(M_{2}\right) \cup \operatorname{dom}\left(\gamma_{2}\right)$, then $\Gamma \vdash M_{1}\left\{x \leftarrow M_{2}\right\}: \tau / \gamma_{1} \wedge d @ \gamma_{2}$.

Lemma 5.3. (Substitution by a variable.) If $\Gamma+\left\{x \mapsto \tau^{\prime}\right\} \vdash M: \tau / \gamma[x \mapsto d]$ and $\Gamma(y)=\tau^{\prime}$, then $\Gamma \vdash M\{x \leftarrow y\}: \tau / \gamma \wedge(y \mapsto d)$.

Lemma 5.4. (Parallel substitution.) If $\Gamma+\left\{\ldots x_{i}: \tau_{i} \ldots\right\} \vdash M: \tau / \gamma_{M}\left[\ldots x_{i} \mapsto\right.$ $\left.d_{i} \ldots\right]$, and for all $j \in\{1 \ldots n\}, \Gamma \vdash M_{j}: \tau_{j} / \gamma_{j}$ with for all $i, j, x_{i} \notin F V\left(M_{j}\right) \cup$ $\operatorname{dom}\left(\gamma_{j}\right)$, then $\Gamma \vdash M\left\{\ldots x_{i} \leftarrow M_{i} \ldots\right\}: \tau / \gamma_{M} \wedge \bigwedge_{i} d_{i} @ \gamma_{i}$.

We then show the standard properties of subject reduction (reduction preserves typing) and progress (well-typed terms are not stuck).

Lemma 5.5. (Subject reduction.) If $\Gamma \vdash M: \tau / \gamma$ and $M \rightarrow M^{\prime}$, then $\Gamma \vdash M^{\prime}$ : $\tau / \gamma$.

Lemma 5.6. (Progress.) If $\Gamma \vdash M: \tau / \gamma$ and $\gamma \geq 1$, then either $M$ is a value, or there exists $M^{\prime}$ such that $M \rightarrow M^{\prime}$.

The soundness of $\lambda_{B}$ follows from lemmas 5.5 and 5.6.

### 5.2 Soundness of the translation

The goal of this section is to prove the soundness of our approach, in the sense that a well-typed $C M S_{v}$ expression translates to a well-typed $\lambda_{B}$ expression. The soundness of $\lambda_{B}$ then ensures that the translation evaluates correctly.

$$
\begin{aligned}
\llbracket \tau_{1} \rightarrow \tau_{2} \rrbracket & =\tau_{1} \xrightarrow{0} \tau_{2} \\
\llbracket \text { int } \rrbracket & =\text { int } \\
\llbracket \text { bool } & =\text { bool } \\
\llbracket\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\} \rrbracket & =\left\langle X: \llbracket \mathcal{O}(X) \rrbracket \rrbracket_{X, \mathcal{D}, \mathcal{I}} \mid X \in \operatorname{dom}(\mathcal{O})\right\rangle \text { if } \vdash\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\} \\
\llbracket \mathcal{T} \rrbracket X, \mathcal{D}, \mathcal{I} & =\llbracket \mathcal{I}_{1} \rrbracket \xrightarrow{\chi_{1}((n-1)} \llbracket \mathcal{T}_{2} \rrbracket \xrightarrow{\chi_{2}+(n-2)} \ldots \llbracket \mathcal{T}_{n} \rrbracket \xrightarrow{\chi_{n}} \llbracket \mathcal{T} \rrbracket \\
& \text { where }\left(\mathcal{T}_{1}^{\chi_{1}}, \ldots, \mathcal{T}_{n}^{\chi n}\right)=F C T_{\mathcal{D}}(X, \mathcal{I})
\end{aligned}
$$

Fig. 10. Translation of $C M S_{v}$ types into $\lambda_{B}$ types

| Core terms: | $\begin{aligned} \bar{C}::= & x^{\mathcal{T}} \mid c s t^{\mathcal{T}} \\ & \left\|\lambda x . \bar{C}^{\mathcal{T}}\right\|\left(\bar{C}_{1} \bar{C}_{2}\right)^{\mathcal{T}} \\ & \mid \bar{E} . X^{\mathcal{T}} \end{aligned}$ | variables, constants abstraction, application component projection |
| :---: | :---: | :---: |
| Mixin terms: | $\begin{aligned} \bar{E}::= & \overline{\bar{C}} \\ & \mid\left\langle\langle; \bar{o}\rangle^{\mathcal{T}}\right. \\ & \mid\left(\overline{\left.\bar{E}_{1}+\bar{E}_{2}\right)^{\mathcal{T}}}\right. \\ & \mid(\bar{E}[X \leftarrow Y])^{\mathcal{T}} \\ & \mid(\bar{E}!X)^{\mathcal{T}} \\ & \mid(\bar{E} \backslash X)^{\mathcal{T}} \\ & \mid(\operatorname{close}(\bar{E}))^{\mathcal{T}} \end{aligned}$ | core term mixin structure sum rename $X$ to $Y$ freeze $X$ delete $X$ close |
| Output assign | $\bar{o}::=X_{i} \stackrel{i \in I}{\mapsto} \bar{E}_{i}$ |  |

Fig. 11. Syntax of type-annotated $C M S_{v}$ terms
To state the soundness of the translation, we need to set up a translation from source types to $\lambda_{B}$ types. We start by defining useful operations on graphs and signatures in Figure 9. We define $F C T_{\mathcal{D}}(X, \mathcal{I})$ as the list of the types and valuations of the predecessors of $X$ in $\mathcal{D}$ according to $\mathcal{I}$, ordered lexicographically. Then, $\operatorname{Sources}(\mathcal{D})$ and $\operatorname{Sinks}(\mathcal{D})$ are simply the sets of predecessors and successors of any node in $\mathcal{D}$. The translation of types is presented in Figure 10. A natural translation for environments follows, defined by $\llbracket \Gamma \rrbracket=\llbracket \rrbracket \circ \Gamma$. Moreover, we define the initial degree environment corresponding to a type environment as $d^{o}(\Gamma)=\underline{0} \circ \Gamma$, that is to say the function equal to 0 on $\operatorname{dom}(\Gamma)$ and $\infty$ elsewhere. In the sequel, we will often use valuations as degrees. It is worth noticing that for all valuations $\chi_{1}$, and $\chi_{2}, \min \left(\chi_{1}, \chi_{2}\right)=\chi_{1} \wedge \chi_{2}=\chi_{1} @ \chi_{2}$.

As the translation operates on annotated well-typed terms, we define an annotated syntax in Figure 11. The type system for annotated terms is exactly the same, except that it looks more like a well-formedness judgment $\Gamma \vdash \bar{E}$. Thus a derivation for a standard term yields a correct derivation for the corresponding annotated term. We denote by $\bar{E}$ the annotated term corresponding to a derivation of $E$, which should be clear from the context. A well-formed annotated term is a term whose annotations are all well-formed types. We consider only well-formed annotated terms in the following.

We define $\operatorname{IsRec}(E)$ as 1 if $E$ is an abstraction $\lambda x . C$, and 0 otherwise, and extend this definition to annotated expressions.

Theorem 5.7. (Soundness of the translation.) If $\Gamma \vdash E: \mathcal{T}$, then $\llbracket \Gamma \rrbracket \vdash \llbracket \bar{E} \rrbracket$ : $\llbracket \mathcal{T} \rrbracket / d^{o}(\Gamma)+\operatorname{IsRec}(E)$.

See appendix C for the full proof. Notice that this result holds for non-empty contexts $\Gamma$; in conjunction with the compositional nature of the translation, this ensures that our compilation scheme is applicable (and sound) not only to closed programs, but also to terms with free variables as can arise during separate compilation.

## 6. RELATED WORK

### 6.1 Mixin-based inheritance and object-oriented traits

The notion of mixin originates in the object-oriented language Flavors [Moon 1986], and was further investigated both as a linguistic device addressing many of the shortcomings of inheritance [Flatt et al. 1998; Findler and Flatt 1998] and as a semantic foundation for inheritance [Cook 1989]. An issue with mixin classes that is generally not addressed is the treatment of instance fields and their initialization. Mixin classes where instance fields can be initialized by arbitrary expressions raise exactly the same problems of detecting cyclic dependencies that we have addressed in this paper in the context of call-by-value mixin modules. Initialization can also be performed by an initialization method named init or some other conventional name, but this breaks data encapsulation.
The notion of traits [Black et al. 2003] shares several key features with mixin modules. Traits are collections of named methods that can be combined together and with regular class definitions using various operators such as sum, overriding, aliasing and exclusion. Traits contain only methods but not instance fields; therefore, initialization of instance fields is again not addressed.

### 6.2 Language designs with mixin modules

Bracha [Bracha 1992] formulated the concept of mixin-based inheritance (sum) independently of an object-oriented setting. His mixins do not address the initialization issue. Duggan and Sourelis [1996] transposed Bracha's mixin concept to the ML module system. Their mixin module system supports extensible functions and datatypes: a function defined by cases can be split across several mixins, each mixin defining only certain cases, and similarly a datatype (sum type) can be split across several mixins, each mixin defining only certain constructors; a composition operator then stitches together these cases and constructors. The recursion problem is avoided by allowing only functions ( $\lambda$-abstractions) in the combinable parts of mixins, while initialization code goes into a separate, non-combinable part of mixins. Their compilation scheme (into ML modules) is less efficient than ours, since the fixpoint defining a function is computed at each call, rather than only once at mixin combination time as in our system.

Flatt and Felleisen [1998] introduce the closely related concept of units, which adapt Bracha's ideas to Scheme and ML. A first difference with our proposal is that units do not feature late binding. Moreover, the initialization problem is handled differently. Their implementation of units for Scheme allows arbitrary computations within the definitions of unit components, and evaluates these computations like Scheme's letrec construct. Thus, ill-founded recursions are not prevented statically. The formalization of units in [Flatt and Felleisen 1998, section 4] restricts definitions to syntactic values, but includes an initialization expression in
each unit. This initialization expression can perform arbitrary computations and refer to the variables bound by the definitions, but is evaluated for its side-effects only. As in Duggan and Sourelis' system, this approach prevents the creation of ill-founded recursive definitions, but is less flexible than our approach.

### 6.3 Mixin calculi

Ancona and Zucca [1998; 1999; 2002] develop a theory of mixins, abstracting over much of the core language, and show that it can encode the pure $\lambda$-calculus, as well as Abadi and Cardelli's object calculus. The emphasis is on providing a calculus, with reduction rules but no fixed reduction strategy, and nice confluence properties. Another calculus of mixins is the m-calculus [Wells and Vestergaard 2000], which is very similar to $C M S$ in many aspects, but is not based on any core language, using only variables instead. The emphasis is put on the equational theory, allowing for example to replace some variables with their definition inside a structure, or to garbage collect unused components, yielding a powerful theory. Neither Ancona and Zucca nor Wells and Vestergaard attempt to statically control recursive definitions, performing on-demand unwinding instead. Still, some care is required when unwinding definitions inside a structure, because of confluence problems [Ariola and Blom 2002].

### 6.4 Recursive modules in ML

Crary et al. [1999], Dreyer et al. [2001], and Russo [2001] extend the Standard ML module system with mutually recursive structures via a structure rec binding. Like mixins, this construct addresses ML's cross-module recursion problem; unlike mixins, it does not support late binding and incremental programming. The structure rec binding does not lend itself directly to separate compilation (the definitions of all mutually recursive modules must reside in the same source file), although separate compilation can be recovered by functorizing each recursive module over the others. ML structures contain type components in addition to value components, and this raises delicate static typing issues that we have not yet addressed within our $C M S_{v}$ framework. Crary et al. formalize static typing of recursive structure using recursively-defined signatures and the phase distinction calculus, while Russo remains closer to Standard ML's static semantics. Concerning ill-founded recursive value definitions, Russo does not attempt to detect them statically, relying on run-time tests to catch them during evaluation. Crary et al. statically require that all components of recursive structures are syntactic values. This is safe, but less flexible than our component-per-component dependency analysis.

### 6.5 Type systems for well-founded recursion

The type system for $\lambda_{B}$ presented in section 5 is a refinement of the type system introduced by Boudol [2003]. Dreyer [2004] and Dreyer et al. [2003] propose a different type system to guarantee safe call-by-value evaluation of generalized recursive definitions of the form let rec $x=M x$ in $N$. Their system can be viewed as an effect system that tracks the (pro forma) effect of using the value of a recursively-bound variable. The typing rules ensure that no such use can occur before the recursive definition has been fully evaluated. This type system appears expressive enough to show that the terms produced by our compilation scheme do
not get stuck on an illegal recursive definition. Moreover, its type soundness proof appears simpler than that of our type system. A drawback of Dreyer's system for our purpose is that it requires "boxing" and "unboxing" annotations in terms and in type expressions. It is not immediately obvious how to extend the compilation scheme given in section 4 to insert the correct annotations.

### 6.6 Connections with object-oriented type systems

Bono et al. [1999] use a notion of dependency graph in the context of a type system for extensible and incomplete objects. However, they do not distinguish between " 0 " and " 1 " dependencies, since the fact that objects contain only methods but no immediate computations precludes immediate dependencies between methods.

## 7. CONCLUSIONS AND FUTURE WORK

As a first step towards a full mixin module system for ML, we have developed a call-by-value variant of Ancona and Zucca's calculus of mixins. The main technical innovation of our work is the use of dependency graphs in mixin signatures, statically guaranteeing that cross-module recursive definitions are well founded, yet leaving maximal flexibility in mixing recursive function definitions and non-recursive computations within a single mixin. Dependency graphs also allow a separate compilation scheme for mixins where fixpoints are taken as early as possible, i.e. during mixin initialization rather than at each component access.

Our $\lambda_{B}$ target calculus can be compiled efficiently down to machine code, using the "in-place updating" trick outlined in [Cousineau et al. 1987] and formalized in [Hirschowitz et al. 2003; Hirschowitz 2003] to implement the non-standard let rec construct.

In this paper, the dynamic semantics of $C M S_{v}$ is given by translation. A direct reduction semantics is desirable to allow finer reasoning on the evaluation of mixins. More recent work [Hirschowitz et al. 2004; Hirschowitz 2003] develops a call-byvalue reduction semantics for a calculus of mixins called MM, closely related to $C M S_{v}$.

The translation semantics of $C M S_{v}$ raises another issue that is better addressed in the reduction semantics of MM: programmer control of evaluation order. In $C M S_{v}$, when a mixin is closed, its definitions are evaluated in an order that is only partially determined by a topological sort of its dependency graph. Moreover, the freeze operator duplicates the definition of the frozen component into the components that use it, resulting in multiple evaluations of the frozen component later. These two features are problematic when the core language is imperative. In MM, frozen components are never duplicated, but turned into local (nameless) definitions instead; and the evaluation order of components is unambiguously determined by a combination of the initial ordering of definitions in structures, and programmer-supplied "fake dependency" annotations on definitions.

The price to pay for this better control of evaluation order is that MM does not lend itself to a type-directed compilation scheme like the one presented in this paper. Since local definitions do not appear in mixin signatures, it is not possible to determine when and where they should be evaluated based on the signatures of the mixins involved, like the compilation scheme presented in this paper does. Indeed, the only known implementation scheme for MM is interpretative in nature
and relies on run-time interpretation of dependency graphs. The overhead of this interpretation is acceptable if mixins are second-class (like ML modules), but if mixins are first-class values, the compilation scheme for $C M S_{v}$ presented here is much more efficient.

A drawback of dependency graphs is that programmers must (in principle) provide them explicitly when declaring a mixin signature, e.g. for a deferred sub-mixin component. This could make programs quite verbose. Future work includes the design of a concrete syntax for mixin signatures that alleviate this problem in the most common cases. A more ambitious approach is to infer dependency graphs entirely, by generating constraints between formal variables ranging over dependency graphs, and solving these constraints incrementally.

The next step towards mixins for ML is to support type definitions and declarations as components of mixins. While these type components account for most of the complexity of ML module typing, we are confident that we can extend to mixins the body of type-theoretic work already done for ML modules [Harper and Lillibridge 1994; Leroy 1994] and recursive modules [Crary et al. 1999; Dreyer et al. 2001].

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## ELECTRONIC APPENDIX

The electronic appendix for this article can be accessed in the ACM Digital Library by visiting the following URL: http://www.acm.org/pubs/citations/ journals/toplas/2005-27-5/p1-Hirschowitz.pdf.

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## A. SOUNDNESS OF GRAPH OPERATIONS

In the following, we write $f s t(P)$ and $\operatorname{last}(P)$ for the first (respectively, last) node of a path $p$. We write $[X]$ for the zero-length path consisting of node $X$. If $f s t(P)=Y$, we write $(X \xrightarrow{\chi} Y):: P$ for the path obtained by prepending the edge $X \xrightarrow{\chi} Y$ to the path $p$. The valuation $\nu(P)$ of a path $P$ is defined inductively by $\nu([X])=1$ and $\nu((X \xrightarrow{\chi} Y):: P)=\min (\chi, \nu(P))$. Thus, a graph $\mathcal{D}$ is safe if and only if all paths $p$ of $\mathcal{D}$ such that $f s t(P)=\operatorname{last}(P)$ are such that $\nu(P)=1$.

Lemma A.1. If $\mathcal{D}$ is a safe dependency graph, then the graphs $\mathcal{D}[X \leftarrow Y], \mathcal{D} \backslash X$ and $\mathcal{D}!X$ are safe.

Proof. For each operation, we show that for all path in the result graph, there exists a corresponding path with the same valuation in $\mathcal{D}$.

Renaming: Let $\mathcal{D}^{\prime}=\mathcal{D}[X \leftarrow Y]=\{A\{X \leftarrow Y\} \xrightarrow{\chi} B\{X \leftarrow Y\} \mid A \xrightarrow{\chi} B \in \mathcal{D}\}$, and let $P$ be a path of $\mathcal{D}^{\prime}$, with valuation $\chi$, and $f s t(P)=A$ and $\operatorname{last}(P)=B$. By induction on the length of $P$, we find a path with same valuation in $\mathcal{D}$, such that $f s t(P)=A\{Y \leftarrow X\}$ and $\operatorname{last}(P)=B\{Y \leftarrow X\}$.

Consider first the base case $P=[Z]$ for some name $Z$ mentioned in $\mathcal{D}^{\prime}$. All edges of $\mathcal{D}^{\prime}$ are of the form $A\{X \leftarrow Y\} \xrightarrow{\chi} B\{X \leftarrow Y\}$, where the corresponding edge $A \xrightarrow{\chi} B$ is in $\mathcal{D}$. Hence, there is a name $Z^{\prime}$ mentioned in $\mathcal{D}$ such that $Z=Z^{\prime}\{X \leftarrow$ $Y\}$. If $Z=Y$, then $Z^{\prime}=X$, because $Y$ cannot be mentioned in $\mathcal{D}$ by definition of the renaming operation, and then the path $[X]$ in $\mathcal{D}$ has same valuation as $P$, and the right first and last nodes. If $Z \neq Y$, then $Z=Z^{\prime}$ and the path $\left[Z^{\prime}\right]$ of $\mathcal{D}$ has the expected valuation, first and last nodes.

Now, assume the result for $P^{\prime}$ and consider $P=(A \xrightarrow{\chi} B):: P^{\prime}$, with $f s t\left(P^{\prime}\right)=B$. Let $\operatorname{last}\left(P^{\prime}\right)=C$ and $\chi^{\prime}=\nu\left(P^{\prime}\right)$. By induction hypothesis, there is a path $P^{\prime \prime}$ of $\mathcal{D}$, from $B\{Y \leftarrow X\}$ to $C\{Y \leftarrow X\}$, with valuation $\chi^{\prime}$. By definition of $\mathcal{D}^{\prime}$ the edge

[^1]
## App-2 • T. Hirschowitz and X.Leroy



Fig. 12. Summary of degree operations
$A\{Y \leftarrow X\} \xrightarrow{\chi} B\{Y \leftarrow X\}$ is in $\mathcal{D}$. Therefore, the path $(A\{Y \leftarrow X\} \xrightarrow{\chi} B\{Y \leftarrow$ $X\}):: P^{\prime \prime}$ is in $\mathcal{D}$ as well. It has the expected first and last nodes, and its valuation is $\min \left(\chi, \chi^{\prime}\right)=\nu(P)$.
It follows that every cycle in $\mathcal{D}^{\prime}$ corresponds to a cycle in $\mathcal{D}$ with the same valuation. Since $\mathcal{D}$ is safe, $\mathcal{D}^{\prime}$ is safe as well.

Deletion: The result is straightforward, since all edges of the resulting graph $\mathcal{D}^{\prime}$ are already present in $\mathcal{D}$.

Freezing: Let $\mathcal{D}^{\prime}=\mathcal{D}!X=\left(\mathcal{D} \cup \mathcal{D}_{\text {around }}\right) \backslash \mathcal{D}_{\text {remove }}$, where $\mathcal{D}_{\text {around }}$ and $\mathcal{D}_{\text {remove }}$ are defined in section 3.2, and let $P$ be a path of $\mathcal{D}^{\prime}$, with valuation $\chi$, and $f s t(P)=A$ and $\operatorname{last}(P)=B$. By induction on the length of $P$, we construct a path from $A$ to $B$ in $\mathcal{D}$ with the same valuation.

For the base case $P=[A]$, we have $A=B$. Since the freezing operation does not introduce new names, all names appearing in $\mathcal{D}^{\prime}$ are already in $\mathcal{D}$; therefore, $P$ is also a path of $\mathcal{D}$, obviously with valuation 1 .

Consider now $P=(A \xrightarrow{\chi} C):: P^{\prime}$, with $f s t\left(P^{\prime}\right)=C$ and $\operatorname{last}\left(P^{\prime}\right)=B$. By induction hypothesis, there is a path $P^{\prime \prime}$ in $\mathcal{D}$ from $C$ to $B$ such that $\nu\left(P^{\prime \prime}\right)=$ $\nu\left(P^{\prime}\right)$. We now argue by cases on the edge $A \xrightarrow{\chi} C$ : by definition of the freeze operation, it can either be in $\mathcal{D}$ or in $\mathcal{D}_{\text {around }}$. If the edge $A \xrightarrow{\chi} C$ comes from $\mathcal{D}$, the path $A \xrightarrow{\chi} C:: P^{\prime \prime}$ is then clearly a path of $\mathcal{D}$, with the expected valuation and endpoints. If the edge $A \xrightarrow{\chi} C$ comes from $\mathcal{D}_{\text {around }}$, there exist $\chi_{1}$ and $\chi_{2}$ such that $A \xrightarrow{\chi_{1}} X \in \mathcal{D}$ and $X \xrightarrow{\chi_{2}} C \in \mathcal{D}$ and $\chi=\min \left(\chi_{1}, \chi_{2}\right)$. Hence, the path $\left(A \xrightarrow{\chi_{1}} X\right)::\left(X \xrightarrow{\chi_{2}} C\right):: P^{\prime \prime}$ is a path of $\mathcal{D}$ from $A$ to $B$, with valuation $\min \left(\min \left(\chi_{1}, \chi_{2}\right), \nu\left(P^{\prime \prime}\right)\right)=\min \left(\chi, \nu\left(P^{\prime}\right)\right)=\nu(P)$.

## B. SOUNDNESS OF THE TARGET LANGUAGE

To simplify the proofs, we prove the soundness on a subset $\lambda_{\bar{B}}$ of $\lambda_{B}$ that excludes constants, record construction and access, and the let binding. It is entirely straightforward to extend the proofs to the omitted constructs.

## B. 1 Properties of degrees

We start the proof with a number of algebraic lemmas on degrees and degree operations. Figure 12 re-states the definitions of the operations on degrees. The following lemmas should be read as universally quantified over the degrees $d, d^{\prime}, d_{1}, d_{2}, d_{3}$. We adopt the convention that @ has highest precedence, followed by $\wedge$, and then

+ and.-
Lemma B.1.
(1) $\left(d_{1}+1\right) @ d_{2} \leq d_{1} @ d_{2}+1$.
(2) $\left(d_{1} \wedge d_{2}\right) @ d_{3}=d_{1} @ d_{3} \wedge d_{2} @ d_{3}$.
(3) $d_{1} @\left(d_{2} \wedge d_{3}\right)=d_{1} @ d_{2} \wedge d_{1} @ d_{3}$.
(4) $\left(d_{1} @ d_{2}\right) @ d_{3}=d_{1} @\left(d_{2} @ d_{3}\right)$.
(5) $(d-n) @ d^{\prime}=d @ d^{\prime}-n$.
(6) If $d+1=d^{\prime}$, then $d^{\prime} \geq 1$ and $d=d^{\prime}-1$.
(7) If $d \neq 0$, then $d-1+1=d$.
(8) $0 @ d \leq d$.
(9) If $d \leq d^{\prime}$ then $d+1 \leq d^{\prime}+1$.
(10) If $d+1 \leq d^{\prime}-1$ then $d+2 \leq d^{\prime}$.
(11) If $d_{2} \geq 1$, then $d_{1} @ d_{3} \leq d_{1} @ d_{2} @ d_{3}$.

Proof.
(1) If $d_{2}=0$, we obtain $0 \leq 1$, which is true. If $d_{2}=\infty$ we obtain $\infty \leq \infty$. Otherwise, the claim reduces to $d_{1}+1 \leq d_{1}+1$.
(2) If $d_{3}=0$, we obtain 0 on both sides of the equality. If $d_{3}=\infty$, both sides are equal to $\infty$. Otherwise we get $d_{1} \wedge d_{2}$ on both sides.
(3) If $d_{2}=0$, both sides are equal to 0 . If $d_{2}=\infty$, then $d_{2} \wedge d_{3}=d_{3}$ and $d_{1} @ d_{2}=\infty$, so both sides are equal to $d_{1} @ d_{3}$. Otherwise, we argue by case on $d_{3}$. If $d_{3}=0$, then we obtain 0 on both sides, and if $d_{3}=\infty$, we obtain $d_{1} @ d_{2}$ for both sides. Otherwise, $d_{2} \wedge d_{3}=n \neq 0$, so $d_{1} @\left(d_{2} \wedge d_{3}\right)=d_{1}=$ $d_{1} \wedge d_{1}=d_{1} @ d_{2} \wedge d_{1} @ d_{3}$.
(4) If $d_{3}=0$, both sides are equal to 0 . If $d_{3}=\infty$, we obtain $\infty$ on both sides. Otherwise, both sides are equal to $d_{1} @ d_{2}$.
(5) Both sides reduce to $\infty$ if $d^{\prime}=\infty$, to 0 if $d^{\prime}=0$, and to $d-1$ otherwise.
(6) By definition of + .
(7) By definition of + and - .
(8) By definition of @.
(9) By definition of + .
(10) Since $d+1$ is strictly positive, $d^{\prime}$ cannot be 0 . Thus, $d^{\prime}=d^{\prime}-1+1$ by property 7 , and the result follows by applying property 9 to $d+1 \leq d^{\prime}-1$.
(11) If $d_{3}=\infty$ or $d_{3}=0$, both sides reduce to $d_{3}$. Otherwise, write $d_{3}=n+1$. Then, $d_{1} @ d_{3}=d_{1}$ and $d_{1} @ d_{2} @ d_{3}=d_{1} @ d_{2}$, hence it simply remains to prove that $d_{1} \leq d_{1} @ d_{2}$. Since $d_{2} \geq 1$, we have only two cases: either $d_{2}=\infty$, in which case $d_{1} @ d_{2}=\infty$ which cannot be less than $d_{1}$; or $d_{2}=m+1$, in which case $d_{1} @ d_{2}=d_{1}$, and the result holds.

This completes the proof.
Lemma B.2. If $\gamma \leq\left(\gamma_{1}-1\right) \wedge d @ \gamma_{2}$, then there exists $\gamma_{1}^{\prime}$ and $\gamma_{2}^{\prime}$ such that $\gamma=\left(\gamma_{1}^{\prime}-1\right) \wedge d @ \gamma_{2}^{\prime}$ and $\gamma_{1}^{\prime} \leq \gamma_{1}$ and $\gamma_{2}^{\prime} \leq \gamma_{2}$.

Proof. We define $\gamma_{1}^{\prime}$ and $\gamma_{2}^{\prime}$ pointwise. Consider a variable $x$. Let $d^{\prime}=$ $\gamma(x), d_{1}=\gamma_{1}(x), d_{2}=\gamma_{2}(x)$. We construct $d_{1}^{\prime}$ and $d_{2}^{\prime}$ such that $d^{\prime}=\left(d_{1}^{\prime}-1\right) \wedge d @ d_{2}^{\prime}$ and $d_{1}^{\prime} \leq d_{1}$ and $d_{2}^{\prime} \leq d_{2}$. If $d^{\prime}=0$, then we can take $d_{1}^{\prime}=d_{2}^{\prime}=0$. If $d^{\prime}=\infty$, then we can take $d_{1}^{\prime}=d_{1}$ and $d_{2}^{\prime}=d_{2}$, because only $\infty$ is greater than $d^{\prime}$. Finally, if $d^{\prime}=n+1$, let $d_{1}^{\prime}=n+2$ and $d_{2}^{\prime}=d_{2}$. By hypothesis we know that $d^{\prime} \leq d @ d_{2}$. Since $d_{1}^{\prime}-1=n+1=d^{\prime}$, we have $\left(d_{1}^{\prime}-1\right) \wedge d @ d_{2}^{\prime}=d_{1}^{\prime}-1=d^{\prime}$. Moreover, since $d^{\prime} \leq d_{1}-1$, we have that $n+1 \leq d_{1}-1$, and therefore ( $d_{1}^{\prime}=n+2 \leq d_{1}$ by lemma B.1. Finally, $d_{2}^{\prime} \leq d_{2}$ trivially holds.

Lemma B.3. If $\gamma \leq\left(\gamma_{1}-1\right) \wedge(x \mapsto d)$, then there exists $\gamma_{1}^{\prime}$ such that $\gamma_{1}^{\prime} \leq \gamma_{1}$ and $\gamma=\left(\gamma_{1}^{\prime}-1\right) \wedge(x \mapsto d)$.

Proof. We proceed as in the previous proof. Consider a variable $y$ and let $d^{\prime}=\gamma(y)$ and $d_{1}=\gamma_{1}(y)$. We construct $d_{1}^{\prime}$ such that $d_{1}^{\prime} \leq d_{1}$ and $d^{\prime}=\left(d_{1}^{\prime}-1\right) \wedge$ $((x \mapsto d)(y))$. If $d_{1}=0$, then $d_{1}^{\prime}=0$ works. Otherwise, we take $d_{1}^{\prime}=d^{\prime}+1$. This definition satisfies the following properties:
-Since $d^{\prime} \leq d_{1}-1$, we have $d^{\prime}+1 \leq d_{1}-1+1$ and $d_{1} \neq 0$. By lemma B.1, it follows that $d_{1}-1+1=d_{1}$, hence $d_{1}^{\prime} \leq d_{1}$.
-From $d^{\prime} \leq\left(d^{\prime}+1-1\right) \leq\left(d_{1}^{\prime}-1\right)$ and $d^{\prime} \leq\left(d_{1}-1\right) \wedge(x \mapsto d)(y) \leq(x \mapsto d)(y)$, it follows that $d^{\prime} \leq\left(d_{1}^{\prime}-1\right) \wedge((x \mapsto d)(y))$.
-Since $d_{1}^{\prime}-1=d^{\prime}$, we have that $\left(d_{1}^{\prime}-1\right) \wedge((x \mapsto d)(y)) \leq d^{\prime}$.
Thus, $d_{1}^{\prime}$ satisfies the claim.
Lemma B.4. Let $n \in \mathbb{N}$. If

$$
\gamma^{\prime} \leq \gamma_{0} \wedge \bigwedge_{i, j \in\{1 \ldots n\}} d_{i} @ d_{i j} @ \gamma_{j} \wedge \bigwedge_{i \in\{1 \ldots n\}} d_{i} @ \gamma_{i}
$$

then there exist $\gamma_{0}^{\prime}, \gamma_{1}^{\prime}, \ldots, \gamma_{n}^{\prime}$ such that $\gamma_{i}^{\prime} \leq \gamma_{i}$, for $i=0, \ldots, n$ and

$$
\gamma^{\prime}=\gamma_{0}^{\prime} \wedge \bigwedge_{i, j \in\{1 \ldots n\}} d_{i} @ d_{i j} @ \gamma_{j}^{\prime} \wedge \bigwedge_{i \in\{1 \ldots n\}} d_{i} @ \gamma_{i}^{\prime} .
$$

Proof. Simply take $\gamma_{0}^{\prime}=\gamma^{\prime}$ and $\gamma_{i}^{\prime}=\gamma_{i}$ for $i=1, \ldots, n$. By transitivity we have $\gamma_{0}^{\prime} \leq \gamma_{0}$ and trivially $\gamma_{i}^{\prime} \leq \gamma_{i}$. It is easy to check that

$$
\gamma_{0}^{\prime} \wedge \bigwedge_{i, j \in\{1 \ldots . . n\}} d_{i} @ d_{i j} @ \gamma_{j}^{\prime} \wedge \bigwedge_{i \in\{1 \ldots n\}} d_{i} @ \gamma_{i}^{\prime} \leq \gamma^{\prime}
$$

by definition of $\gamma^{\prime}$. Moreover, by hypothesis, we know that

$$
\bigwedge_{i, j \in\{1 \ldots n\}} d_{i} @ d_{i j} @ \gamma_{j}^{\prime} \geq \gamma^{\prime} \quad \text { and } \quad \bigwedge_{i \in\{1 \ldots n\}} d_{i} @ \gamma_{i}^{\prime} \geq \gamma^{\prime}
$$

Therefore,

$$
\gamma^{\prime} \leq \gamma_{0}^{\prime} \wedge \bigwedge_{i, j \in\{1 \ldots n\}} d_{i} @ d_{i j} @ \gamma_{j}^{\prime} \wedge \bigwedge_{i \in\{1 \ldots n\}} d_{i} @ \gamma_{i}^{\prime}
$$

and the expected equality follows.
Lemma B.5. If $\gamma[x \mapsto d]=\left(\gamma_{1}-1\right) \wedge d_{0} @ \gamma_{2}$ then there exist $\gamma_{1}^{\prime}$, $\gamma_{2}^{\prime}$, $d_{1}, d_{2}$ such that $\gamma_{1}=\gamma_{1}^{\prime}\left[x \mapsto d_{1}\right], \gamma_{2}=\gamma_{2}^{\prime}\left[x \mapsto d_{2}\right]$, and $\gamma=\left(\gamma_{1}^{\prime}-1\right) \wedge d_{0} @ \gamma_{2}^{\prime}$.
ACM Transactions on Programming Languages and Systems, Vol. 27, No. 5, September 2005.

Proof. Let $d_{1}=\gamma_{1}(x)$ and $d_{2}=\gamma_{2}(x)$. Let $\gamma_{1}^{\prime}$ be the function associating $\gamma_{1}(y)$ to every variable $y \neq x$ and such that $\gamma_{1}^{\prime}(x)=\gamma(x)+1$, which we can write $\gamma_{1}[x \mapsto \gamma(x)+1]$. Let $\gamma_{2}^{\prime}$ be the function associating $\gamma_{2}(y)$ to every variable $y \neq x$ and such that $\gamma_{2}^{\prime}(x)=\infty$, which we can write $\gamma_{2}[x \mapsto \infty]$. We have trivially $\gamma_{1}=\gamma_{1}^{\prime}\left[x \mapsto d_{1}\right]$ and $\gamma_{2}=\gamma_{2}^{\prime}\left[x \mapsto d_{2}\right]$. We now check the third property. On $x$,

$$
\gamma(x)=(\gamma(x)+1-1) \wedge d_{0} @ \infty=\left(\gamma_{1}^{\prime}(x)-1\right) \wedge d_{0} @ \gamma_{2}^{\prime}(x)
$$

On $y \neq x$,

$$
\gamma(y)=\left(\gamma_{1}(y)-1\right) \wedge d_{0} @ \gamma_{2}(y)=\left(\gamma_{1}^{\prime}(y)-1\right) \wedge d_{0} @ \gamma_{2}^{\prime}(y)
$$

This is the expected result.
Lemma B.6. If $\gamma[x \mapsto d]=\gamma_{0} \wedge\left(\bigwedge_{i, j \in\{1 \ldots n\}} d_{i} @ d_{i j} @ \gamma_{j}\right) \wedge\left(\bigwedge_{i} d_{i} @ \gamma_{i}\right)$, then there exist $\gamma_{0}^{\prime}$ and a $\gamma_{i}^{\prime}$ for each $i$, such that $\gamma_{0}^{\prime}\left[x \mapsto d_{0}\right]=\gamma_{0}, \gamma_{i}^{\prime}\left[x \mapsto d_{i}^{\prime}\right]=\gamma_{i}$, and $\gamma=\gamma_{0}^{\prime} \wedge\left(\bigwedge_{i, j \in\{1 \ldots n\}} d_{i} @ d_{i j} @ \gamma_{j}^{\prime}\right) \wedge\left(\bigwedge_{i} d_{i} @ \gamma_{i}^{\prime}\right)$, with $d_{0}=\gamma_{0}(x)$ and $d_{i}^{\prime}=\gamma_{i}(x)$ for all $i$.

Proof. Take $\gamma_{0}^{\prime}=\gamma_{0}[x \mapsto \gamma(x)]$ and $\gamma_{i}^{\prime}=\gamma_{i}[x \mapsto \infty]$ for all $i$. We check that the expected properties hold as in the previous proof.

## B. 2 Weakening lemmas

We now prove two "weakening" lemmas showing that the typing judgement still holds if the degree environment $\gamma$ is replaced by another environment $\gamma^{\prime} \leq \gamma$, or if the degree $\gamma(x)$ of an unused variable $x$ is changed.

Lemma B.7. (Degree restriction.) If $\gamma^{\prime} \leq \gamma$ and $\Gamma \vdash M: \tau / \gamma$, then $\Gamma \vdash M$ : $\tau / \gamma^{\prime}$.

Proof. We reason by induction on the typing derivation of $M$, and by case on the last typing rule used. (Refer to Figure 8 for the typing rules of $\lambda_{B}$.)
Rule (var), $M=x$. We know that $\Gamma(x)=\tau$ and $\gamma(x)=0 \geq \gamma^{\prime}(x)$, so $\gamma^{\prime}(x)=0$ and we can apply the axiom (var) again.
Rule(abstr), $M=\lambda x . M_{1}$. Given the typing rules, we have a derivation of $\Gamma+\{x \mapsto$ $\left.\tau_{1}\right\} \vdash M_{1}: \tau_{2} /(\gamma-1)[x \mapsto d]$ with $\tau=\tau_{1} \xrightarrow{d} \tau_{2}$. Notice that $\left(\gamma^{\prime}-1\right)[x \mapsto d] \leq$ $(\gamma-1)[x \mapsto d]$. Therefore, by induction hypothesis, we have a derivation of $\Gamma+\{x \mapsto$ $\left.\tau_{1}\right\} \vdash M_{1}: \tau_{2} /\left(\gamma^{\prime}-1\right)[x \mapsto d]$. The expected result follows by another application of the rule (abstr).
Rule (app), $M=M_{1} M_{2}$. By typing hypothesis, we have derivations for $\Gamma \vdash M_{1}$ : $\tau^{\prime} \xrightarrow{d} \tau / \gamma_{1}$ and $\Gamma \vdash M_{2}: \tau^{\prime} / \gamma_{2}$, with $\gamma=\left(\gamma_{1}-1\right) \wedge d @ \gamma_{2}$. By lemma B.2, we construct $\gamma_{1}^{\prime}$ and $\gamma_{2}^{\prime}$, such that $\gamma_{1}^{\prime} \leq \gamma_{1}, \gamma_{2}^{\prime} \leq \gamma_{2}$ and $\gamma^{\prime}=\left(\gamma_{1}^{\prime}-1\right) \wedge d @ \gamma_{2}^{\prime}$. Applying the induction hypothesis twice, we obtain derivations for $\Gamma \vdash M_{1}: \tau^{\prime} \xrightarrow{d} \tau / \gamma_{1}^{\prime}$ and $\Gamma \vdash M_{2}: \tau^{\prime} / \gamma_{2}^{\prime}$, and we can apply the rule (app) again to obtain the expected result.
Rule (appvar), $M=M_{1} x$. We have a derivation for $\Gamma \vdash M_{1}: \tau^{\prime} \xrightarrow{d} \tau / \gamma_{1}$ with $\Gamma(x)=\tau^{\prime}$ and $\gamma=\left(\gamma_{1}-1\right) \wedge d$. Hence, $\gamma^{\prime} \leq\left(\gamma_{1}-1\right) \wedge(x \mapsto d)$. Applying lemma

## App-6 • T. Hirschowitz and X.Leroy

B.3, we obtain $\gamma_{1}^{\prime}$ such that $\gamma_{1}^{\prime} \leq \gamma_{1}$ and $\gamma^{\prime}=\left(\gamma_{1}^{\prime}-1\right) \wedge(x \mapsto d)$. We can apply rule (appvar) again to derive the expected judgment.

Rule (rec), $M=$ let rec $\ldots x_{i}=M_{i} \ldots$ in $N$. By typing hypothesis, we have

$$
\begin{gathered}
\Gamma+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash N: \tau / \gamma_{0}\left[\ldots x_{j} \mapsto d_{j} \ldots\right] \\
\Gamma+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash M_{i}: \tau_{i} / \gamma_{i}\left[\ldots x_{j} \mapsto d_{i j} \ldots\right] \\
\text { for all } i, j, d_{i j} \geq 1 \\
\text { for all } i, j, k, d_{i k} \leq d_{i j} @ d_{j k} \\
\gamma=\gamma_{0} \wedge\left(\bigwedge_{i} d_{i} @ \gamma_{i}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ \gamma_{j}\right) .
\end{gathered}
$$

Using lemma B.4, we take $\gamma_{N}^{\prime}=\gamma^{\prime}$ and for all $i, \gamma_{i}^{\prime}=\gamma_{i}$, knowing that $\gamma_{N}^{\prime} \leq \gamma_{0}$ and $\gamma^{\prime}=\gamma_{N}^{\prime} \wedge\left(\bigwedge_{i} d_{i} @ \gamma_{i}^{\prime}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ \gamma_{j}^{\prime}\right)$. By induction hypothesis, we obtain a derivation of $\Gamma+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash N: \tau / \gamma_{N}^{\prime}\left[\ldots x_{j} \mapsto d_{j} \ldots\right]$. Hence we can derive $\Gamma \vdash M: \tau / \gamma^{\prime}$.

Lemma B.8. (Degree weakening.) If $\Gamma \vdash M: \tau / \gamma[x \mapsto d]$ and $x \notin F V(M)$, then $\Gamma \vdash M: \tau / \gamma$.

Proof. The proof is by induction on the typing derivation of $M$ and by case on the last rule used.

Rule (var), $M=y$. Since $x \notin F V(M)$, we have $x \neq y$. By typing hypotheses, $\gamma(y)=0$ and $\Gamma(y)=\tau$. It follows that $\Gamma \vdash M: \tau / \gamma$.
Rule (abstr), $M=\lambda y . M_{1}$, where $y$ is fresh. The premise of the typing rule holds: $\Gamma+\left\{y \mapsto \tau_{1}\right\} \vdash M_{1}: \tau_{2} /(\gamma[x \mapsto d]-1)\left[y \mapsto d_{0}\right]$ and $\tau=\tau_{1} \xrightarrow{d_{0}} \tau_{2}$. Obviously, $(\gamma[x \mapsto d]-1)\left[y \mapsto d_{0}\right]=(\gamma-1)\left[y \mapsto d_{0}\right][x \mapsto d-1]$. Hence, by induction hypothesis we obtain $\Gamma+\left\{y \mapsto \tau_{1}\right\} \vdash M_{1}: \tau_{2} /(\gamma-1)\left[y \mapsto d_{0}\right]$ and the expected result follows by rule (abstr).

Rule (app), $M=M_{1} M_{2}$. We have $\Gamma \vdash M_{1}: \tau^{\prime} \xrightarrow{d_{0}} \tau / \gamma_{1}$ and $\Gamma \vdash M_{2}: \tau^{\prime} / \gamma_{2}$ with $\gamma[x \mapsto d]=\left(\gamma_{1}-1\right) \wedge d_{0} @ \gamma_{2}$. Applying lemma B.5, we obtain $d_{1}, d_{2}, \gamma_{1}^{\prime}$ and $\gamma_{2}^{\prime}$ such that $\gamma=\left(\gamma_{1}^{\prime}-1\right) \wedge d_{0} @ \gamma_{2}^{\prime}, \gamma_{1}^{\prime}\left[x \mapsto d_{1}\right]=\gamma_{1}$ and $\gamma_{2}^{\prime}\left[x \mapsto d_{2}\right]=\gamma_{2}$. By induction hypothesis we can derive $\Gamma \vdash M_{1}: \tau^{\prime} \xrightarrow{d_{0}} \tau / \gamma_{1}^{\prime}$ and $\Gamma \vdash M_{2}: \tau^{\prime} / \gamma_{2}^{\prime}$. The expected result follows by rule (app).

Rule (appvar), $M=M_{1} y$, with $y \neq x$ by hypothesis $x \notin F V(M)$. We have a derivation of $\Gamma \vdash M_{1}: \tau_{1} \xrightarrow{d_{0}} \tau_{2} / \gamma_{1}$ with $\gamma[x \mapsto d]=\left(\gamma_{1}-1\right) \wedge\left(y \mapsto d_{0}\right)$. Take $\gamma_{1}^{\prime}=\gamma_{1}[x \mapsto \gamma(x)+1]$. We have $\gamma_{1}^{\prime}\left[x \mapsto \gamma_{1}(x)\right]=\gamma_{1}$ and $\gamma=\left(\gamma_{1}^{\prime}-1\right) \wedge\left(y \mapsto d_{0}\right)$. The first equality is straightforward, and the second equality follows from the facts that $\gamma(x)=\gamma(x)+1-1$, and for any $z \neq x,\left(\left(\gamma_{1}-1\right) \wedge\left(y \mapsto d_{0}\right)\right)(z)=\left(\left(\gamma_{1}^{\prime}-1\right) \wedge\left(y \mapsto d_{0}\right)\right)(z)$. We then conclude by induction hypothesis as above.

Rule (rec), $M=$ let rec $\ldots x_{i}=M_{i} \ldots$ in $N$. We have

$$
\Gamma+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash N: \tau / \gamma_{N}\left[\ldots x_{j} \mapsto d_{j} \ldots\right]
$$

and for all $i$

$$
\Gamma+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash M_{i}: \tau_{i} / \gamma_{i}\left[\ldots x_{j} \mapsto d_{i j} \ldots\right]
$$

with for all $i, j, k, d_{i k} \leq d_{i j} @ d_{j k}$ and for all $i, j, d_{i j} \geq 1$ and $\gamma[x \mapsto d]=\gamma_{N} \wedge$ $\left(\bigwedge_{i} d_{i} @ \gamma_{i}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ \gamma_{j}\right)$. Lemma B. 6 shows the existence of $\gamma_{N}^{\prime}$ and $\gamma_{i}^{\prime}$ for all $i$ such that $\gamma_{N}^{\prime}\left[x \mapsto d_{N}\right]=\gamma_{N}$, and for all $i \gamma_{i}^{\prime}\left[x \mapsto d_{i}^{\prime}\right]=\gamma_{i}$, and $\gamma=$ $\gamma_{N}^{\prime} \wedge\left(\bigwedge_{i} d_{i} @ \gamma_{i}^{\prime}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ \gamma_{j}^{\prime}\right)$, with $d_{N}=\gamma_{N}(x)$ and for all $i, d_{i}^{\prime}=\gamma_{i}^{\prime}(x)$. Applying the induction hypothesis, we derive

$$
\Gamma+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash N: \tau / \gamma_{N}^{\prime}\left[\ldots x_{j} \mapsto d_{j} \ldots\right]
$$

and for all $i$

$$
\Gamma+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash M_{i}: \tau_{i} / \gamma_{i}^{\prime}\left[\ldots x_{j} \mapsto d_{i j} \ldots\right] .
$$

The result follows by rule (rec).
Lemma B.9. (Type weakening.) If $\Gamma+\left\{x \mapsto \tau^{\prime}\right\} \vdash M: \tau / \gamma$ and $x \notin F V(M)$, then $\Gamma \vdash M: \tau / \gamma$.

Proof. Straightforward by induction on the typing derivation.

## B. 3 Substitution lemmas

We now establish the traditional substitution lemma: a variable can be substituted by a term of the same type without affecting the type of the program. This lemma provides a semantic justification for our definition of @ in relation with what actually happens during the reduction of an application.

Lemma B.10. (Substitution.) If $\Gamma+\left\{x \mapsto \tau^{\prime}\right\} \vdash M_{1}: \tau / \gamma_{1}[x \mapsto d]$, and $\Gamma \vdash$ $M_{2}: \tau^{\prime} / \gamma_{2}$, with $x \notin F V\left(M_{2}\right) \cup \operatorname{dom}\left(\gamma_{2}\right)$, then $\Gamma \vdash M_{1}\left\{x \leftarrow M_{2}\right\}: \tau / \gamma_{1} \wedge d @ \gamma_{2}$.

Proof. We proceed by induction on the typing derivation of $M_{1}$ and case analysis on the last typing rule used. We write $M=M_{1}\left\{x \leftarrow M_{2}\right\}, \Gamma^{\prime}=\Gamma+\left\{x \mapsto \tau^{\prime}\right\}$, and $\gamma_{0}=\gamma_{1} \wedge d @ \gamma_{2}$.

Rule (var), $M_{1}=y$. We have $\Gamma^{\prime}(y)=\tau$ and $\gamma_{1}[x \mapsto d](y)=0$.
If $y=x$, then $M=M_{2}, d=0, \tau=\tau^{\prime}$ and by hypothesis $\Gamma \vdash M: \tau / \gamma_{2}$. By lemma B.7, it suffices to show that $\gamma_{0} \leq \gamma_{2}$ or $\gamma_{1} \wedge 0 @ \gamma_{2} \leq \gamma_{2}$, which is true by lemma B.1.

If $y \neq x$, then $x \notin F V(M)$ and $\Gamma+\left\{x \mapsto \tau^{\prime}\right\} \vdash M: \tau / \gamma_{1}[x \mapsto d]$. By lemmas B. 8 and B. $9, \Gamma \vdash M: \tau / \gamma_{1}$. It suffices to show that $\gamma_{0} \leq \gamma_{1}$, which is trivially true.

Rule (abstr), $M_{1}=\lambda y \cdot M_{3}$, with $y$ fresh. By typing hypothesis, we have

$$
\Gamma^{\prime}+\left\{y \mapsto \tau_{1}\right\} \vdash M_{3}: \tau_{2} / \gamma_{3}\left[y \mapsto d_{0}\right]
$$

with $\tau=\tau_{1} \xrightarrow{d_{0}} \tau_{2}$ and $\gamma_{3}\left[y \mapsto d_{0}\right]=\left(\gamma_{1}[x \mapsto d]-1\right)\left[y \mapsto d_{0}\right]=\left(\gamma_{1}-1\right)[x \mapsto$ $\left.(d-1) ; y \mapsto d_{0}\right]$. Take $M_{3}^{\prime}=M_{3}\left\{x \leftarrow M_{2}\right\}$. By induction hypothesis, we have

## App-8 • T. Hirschowitz and X.Leroy

$\Gamma+\left\{y \mapsto \tau_{1}\right\} \vdash M_{3}^{\prime}: \tau_{2} /\left(\gamma_{1}-1\right)\left[y \mapsto d_{0}\right] \wedge(d-1) @ \gamma_{2}$. Since $y$ is fresh, it does not occur in $\gamma_{2}$, therefore

$$
\begin{aligned}
& \left(\gamma_{1}-1\right)\left[y \mapsto d_{0}\right] \wedge(d-1) @ \gamma_{2} \\
& =\left(\left(\gamma_{1}-1\right) \wedge(d-1) @ \gamma_{2}\right)\left[y \mapsto d_{0}\right] \\
& =\left(\left(\gamma_{1}-1\right) \wedge\left(d @ \gamma_{2}-1\right)\right)\left[y \mapsto d_{0}\right] \text { by lemma B. } 1 \\
& =\left(\left(\gamma_{1} \wedge d @ \gamma_{2}\right)-1\right)\left[y \mapsto d_{0}\right]=\left(\gamma_{0}-1\right)\left[y \mapsto d_{0}\right] .
\end{aligned}
$$

Hence, rule (abstr) concludes $\Gamma \vdash \lambda y \cdot M_{3}^{\prime}: \tau_{1} \xrightarrow{d_{0}} \tau_{2} / \gamma_{0}$, which is the expected result.
Rule (app), $M_{1}=M_{3} M_{4}$. We have $\Gamma^{\prime} \vdash M_{3}: \tau^{\prime \prime} \xrightarrow{d_{0}} \tau / \gamma_{3}$ and $\Gamma^{\prime} \vdash M_{4}: \tau^{\prime \prime} / \gamma_{4}$ and $\gamma_{1}[x \mapsto d]=\left(\gamma_{3}-1\right) \wedge d_{0} @ \gamma_{4}$. By lemma B.5, if $d_{3}=\gamma_{3}(x)$ and $d_{4}=\gamma_{4}(x)$, there exists $\gamma_{3}^{\prime}$ and $\gamma_{4}^{\prime}$ such that $\gamma_{3}^{\prime}\left[x \mapsto d_{3}\right]=\gamma_{3}, \gamma_{4}^{\prime}\left[x \mapsto d_{4}\right]=\gamma_{4}$, and $\gamma_{1}=\left(\gamma_{3}^{\prime}-1\right) \wedge d_{0} @ \gamma_{4}^{\prime}$. By induction hypothesis, if $M_{3}^{\prime}=M_{3}\left\{x \leftarrow M_{2}\right\}$ and $M_{4}^{\prime}=M_{4}\left\{x \leftarrow M_{2}\right\}$, then $\Gamma \vdash M_{3}^{\prime}: \tau^{\prime \prime} \xrightarrow{d_{0}} \tau / \gamma_{3}^{\prime} \wedge d_{3} @ \gamma_{2}$ and $\Gamma \vdash M_{4}^{\prime}: \tau^{\prime \prime} / \gamma_{4}^{\prime} \wedge d_{4} @ \gamma_{2}$. Therefore, by rule (app),

$$
\Gamma \vdash M: \tau /\left(\left(\gamma_{3}^{\prime} \wedge d_{3} @ \gamma_{2}\right)-1\right) \wedge d_{0} @\left(\gamma_{4}^{\prime} \wedge d_{4} @ \gamma_{2}\right)
$$

Moreover, by lemma B.1, the degree environment is equal to

$$
\begin{aligned}
& \left(\gamma_{3}^{\prime}-1\right) \wedge\left(d_{3} @ \gamma_{2}-1\right) \wedge\left(d_{0} @ \gamma_{4}^{\prime}\right) \wedge\left(d_{0} @ d_{4} @ \gamma_{2}\right) \\
& =\gamma_{1} \wedge\left(d_{3} @ \gamma_{2}-1\right) \wedge\left(d_{0} @ d_{4} @ \gamma_{2}\right) \\
& =\gamma_{1} \wedge\left(\left(d_{3}-1_{\wedge} d_{0} @ d_{4}\right) @ \gamma_{2}\right. \\
& =\gamma_{1} \wedge d @ \gamma_{2} \\
& =\gamma_{0}
\end{aligned}
$$

Rule (appvar), $M_{1}=M_{3} y$. As in the (var) case, we argue by case, according to whether $y$ is equal to $x$ or not.

Case $y=x$. Here, $M=M_{3}^{\prime} M_{2}$, where $M_{3}^{\prime}=M_{3}\left\{x \leftarrow M_{2}\right\}$. The typing hypothesis implies $\Gamma^{\prime} \vdash M_{3}: \tau^{\prime \prime} \xrightarrow{d_{0}} \tau / \gamma_{3}\left(^{*}\right)$ and $\Gamma^{\prime}(y)=\Gamma^{\prime}(x)=\tau^{\prime}=\tau^{\prime \prime}$ and $\gamma_{1}[x \mapsto d]=\left(\gamma_{3}-1\right) \wedge\left(y \mapsto d_{0}\right)$. Take $\gamma_{3}^{\prime}=\gamma_{3}\left[x \mapsto \gamma_{1}(x)+1\right]$. We have $\gamma_{1}=\left(\gamma_{3}^{\prime}-1\right)$ and $\gamma_{3}^{\prime}\left[x \mapsto \gamma_{3}(x)\right]=\gamma_{3}$. Thus we can write the premise $\left(^{*}\right)$ as follows

$$
\Gamma^{\prime} \vdash M_{3}: \tau^{\prime \prime} \xrightarrow{d_{0}} \tau / \gamma_{3}^{\prime}\left[x \mapsto \gamma_{3}(x)\right] .
$$

Hence, by induction hypothesis we have

$$
\Gamma \vdash M_{3}^{\prime}: \tau^{\prime \prime} \xrightarrow{d_{0}} \tau / \gamma_{3}^{\prime} \wedge d_{3} @ \gamma_{2}
$$

with $d_{3}=\gamma_{3}(x)$. Then by rule (app), we obtain

$$
\Gamma \vdash M: \tau /\left(\left(\gamma_{3}^{\prime} \wedge d_{3} @ \gamma_{2}\right)-1\right) \wedge d_{0} @ \gamma_{2} .
$$

Notice that $\gamma_{0}=\left(\gamma_{3}^{\prime}-1\right) \wedge d @ \gamma_{2}$. Since $d=\left(d_{3}-1\right) \wedge d_{0}$, it follows that

$$
\gamma_{0}=\left(\gamma_{3}^{\prime}-1\right) \wedge\left(d_{3} @ \gamma_{2}-1\right) \wedge d_{0} @ \gamma_{2}
$$

We therefore have derived the desired judgment.

Case $y \neq x$. Here, $M=M_{3}^{\prime} y$, where $M_{3}^{\prime}=M_{3}\left\{x \leftarrow M_{2}\right\}$. By typing hypothesis, we have $\Gamma^{\prime} \vdash M_{3}: \tau^{\prime \prime} \xrightarrow{d_{0}} \tau / \gamma_{3}\left(^{*}\right)$ and $\Gamma^{\prime}(y)=\Gamma(y)=\tau^{\prime \prime}$ and $\gamma_{1}[x \mapsto d]=$ $\left(\gamma_{3}-1\right) \wedge\left(y \mapsto d_{0}\right)$. Take $\gamma_{3}^{\prime}=\gamma_{3}\left[x \mapsto \gamma_{1}(x)+1\right]$. We have $\gamma_{1}=\left(\gamma_{3}^{\prime}-1\right) \wedge\left(y \mapsto d_{0}\right)$, and $\gamma_{3}^{\prime}\left[x \mapsto \gamma_{3}(x)\right]=\gamma_{3}$. Thus we rewrite the premise $\left(^{*}\right)$ as follows:

$$
\Gamma^{\prime} \vdash M_{3}: \tau^{\prime \prime} \xrightarrow{d_{0}} \tau / \gamma_{3}^{\prime}\left[x \mapsto \gamma_{3}(x)\right]
$$

By induction hypothesis, it follows that

$$
\Gamma \vdash M_{3}^{\prime}: \tau^{\prime \prime} \xrightarrow{d_{0}} \tau / \gamma_{3}^{\prime} \wedge d_{3} @ \gamma_{2}
$$

with $d_{3}=\gamma_{3}(x)$. Then by rule (appvar), we get

$$
\Gamma \vdash M: \tau /\left(\left(\gamma_{3}^{\prime} \wedge d_{3} @ \gamma_{2}\right)-1\right) \wedge\left(y \mapsto d_{0}\right)
$$

which yields by lemma B. 1

$$
\Gamma \vdash M: \tau /\left(\gamma_{3}^{\prime}-1\right) \wedge\left(d_{3} @ \gamma_{2}-1\right) \wedge\left(y \mapsto d_{0}\right)
$$

Moreover,

$$
\begin{aligned}
\gamma_{0} & =\gamma_{1} \wedge d @ \gamma_{2} \\
& =\left(\gamma_{3}^{\prime}-1\right) \wedge\left(y \mapsto d_{0}\right) \wedge d @ \gamma_{2} \\
& =\left(\gamma_{3}^{\prime}-1\right) \wedge\left(y \mapsto d_{0}\right) \wedge\left(d_{3}-1\right) @ \gamma_{2} \\
\text { (because } \gamma_{1}[ & \left.x \mapsto d]=\left(\gamma_{3}-1\right) \wedge\left(y \mapsto d_{0}\right)\right) \\
& =\left(\gamma_{3}^{\prime}-1\right) \wedge\left(y \mapsto d_{0}\right) \wedge\left(d_{3} @ \gamma_{2}-1\right) \quad \text { (by lemma B.1). }
\end{aligned}
$$

Thus, the expected result holds.
Rule (rec), $M=$ let rec $x_{1}=N_{1}$ and $\ldots$ and $x_{n}=N_{n}$ in $N$, where the $x_{i}$ are fresh. By typing hypothesis,

$$
\begin{gathered}
\qquad \begin{array}{l}
\Gamma^{\prime}+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash N: \tau / \gamma_{N}\left[\ldots x_{j} \mapsto d_{j} \ldots\right] \\
\text { for all } i, \Gamma^{\prime}+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash N_{i}: \tau_{i} / \delta_{i}\left[\ldots x_{j} \mapsto d_{i j} \ldots\right]
\end{array} \\
\text { for all } i, j, d_{i j} \geq 1
\end{gathered}
$$

We write $N^{\prime}=N\left\{x \leftarrow M_{2}\right\}$ and for all $i, N_{i}^{\prime}=N_{i}\left\{x \leftarrow M_{2}\right\}$. We have $\gamma_{1}[x \mapsto d]=$ $\gamma_{N} \wedge\left(\bigwedge_{i} d_{i} @ \delta_{i}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ \delta_{j}\right)$. Lemma B. 6 shows that we can construct $\gamma_{N}^{\prime}$ and a $\delta_{i}^{\prime}$ for all $i$ such that $\gamma_{N}^{\prime}\left[x \mapsto d_{N}\right]=\gamma_{N}$, and $\delta_{i}^{\prime}\left[x \mapsto d_{i}^{0}\right]=\delta_{i}$ for all $i$ and $\gamma_{1}=\gamma_{N}^{\prime} \wedge\left(\bigwedge_{i} d_{i} @ \delta_{i}^{\prime}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ \delta_{j}^{\prime}\right)$, with $d_{N}=\gamma_{N}(x)$ and $d_{i}^{0}=\delta_{i}(x)$ for each $i$. Thus, the two premises can be rewritten as follows:

$$
\begin{gathered}
\Gamma^{\prime}+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash N: \tau / \gamma_{N}^{\prime}\left[\ldots x_{j} \mapsto d_{j} \ldots\right]\left[x \mapsto d_{N}\right] \\
\text { for all } i, \Gamma^{\prime}+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash N_{i}: \tau_{i} / \delta_{i}^{\prime}\left[\ldots x_{j} \mapsto d_{i j} \ldots\right]\left[x \mapsto d_{i}^{0}\right]
\end{gathered}
$$

By induction hypothesis, it follows that

$$
\begin{gathered}
\Gamma+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash N^{\prime}: \tau / \gamma_{N}^{\prime}\left[\ldots x_{j} \mapsto d_{j} \ldots\right] \wedge d_{N} @ \gamma_{2} \\
\text { for all } i, \Gamma+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash N_{i}^{\prime}: \tau_{i} / \delta_{i}^{\prime}\left[\ldots x_{j} \mapsto d_{i j} \ldots\right] \wedge d_{i}^{0} @ \gamma_{2}
\end{gathered}
$$

Since the $x_{i}$ s are fresh we have $\gamma_{N}^{\prime}\left[\ldots x_{j} \mapsto d_{j} \ldots\right] \wedge d_{N} @ \gamma_{2}=\left(\gamma_{N}^{\prime} \wedge d_{N} @ \gamma_{2}\right)\left[\ldots x_{j} \mapsto\right.$ $\left.d_{j} \ldots\right]$ and for all $i, \delta_{i}^{\prime}\left[\ldots x_{j} \mapsto d_{i j} \ldots\right] \wedge d_{i}^{0} @ \gamma_{2}=\left(\delta_{i}^{\prime} \wedge d_{i}^{0} @ \gamma_{2}\right)\left[\ldots x_{j} \mapsto d_{i j} \ldots\right]$. We can therefore apply rule (rec) to obtain

$$
\Gamma \vdash M: \tau / \gamma_{N}^{\prime} \wedge d_{N} @ \gamma_{2} \wedge \bigwedge_{i, j} d_{i} @ d_{i j} @\left(\delta_{j}^{\prime} \wedge d_{j}^{0} @ \gamma_{2}\right) \wedge \bigwedge_{i} d_{i} @\left(\delta_{i}^{\prime} \wedge d_{i}^{0} @ \gamma_{2}\right)
$$

According to lemma B.1, the degree environment above is equal to

$$
\begin{aligned}
\gamma_{N}^{\prime} & \wedge\left(d_{N} @ \gamma_{2}\right) \\
& \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ \delta_{j}^{\prime}\right) \\
& \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ d_{j}^{0} @ \gamma_{2}\right) \\
& \wedge\left(\bigwedge_{i}^{i} d_{i} @ \delta_{i}^{\prime}\right) \\
& \wedge\left(\bigwedge_{i} d_{i} @ d_{i}^{0} @ \gamma_{2}\right) .
\end{aligned}
$$

To obtain the expected result, it suffices to prove that this degree environment is equal to $\gamma_{0}$. Since

$$
\gamma_{1}[x \mapsto d]=\gamma_{N} \wedge\left(\bigwedge_{i} d_{i} @ \delta_{i}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ \delta_{j}\right)
$$

we know that

$$
d=\gamma_{N}(x) \wedge\left(\bigwedge_{i} d_{i} @ \delta_{i}(x)\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ \delta_{j}(x)\right)
$$

Therefore, $d=d_{N} \wedge\left(\bigwedge_{i} d_{i} @ d_{i}^{0}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ d_{j}^{0}\right)$. It follows that

$$
\begin{aligned}
\gamma_{0}= & \gamma_{1} \wedge d @ \gamma_{2} \\
= & \gamma_{N}^{\prime} \wedge\left(\bigwedge_{i} d_{i} @ \delta_{i}^{\prime}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ \delta_{j}^{\prime}\right) \\
& \wedge\left(d_{N} \wedge\left(\bigwedge_{i} d_{i} @ d_{i}^{0}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ d_{j}^{0}\right)\right) @ \gamma_{2} \\
= & \gamma_{N}^{\prime} \wedge\left(\bigwedge_{i} d_{i} @ \delta_{i}^{\prime}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ \delta_{j}^{\prime}\right) \\
& \wedge\left(d_{N} @ \gamma_{2}\right) \wedge\left(\bigwedge_{i} d_{i} @ d_{i}^{0} @ \gamma_{2}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ d_{j}^{0} @ \gamma_{2}\right) .
\end{aligned}
$$

This completes the proof.
We now extend the previous lemma to the case of parallel substitution, exploiting the fact that $M\left\{\ldots x_{i} \leftarrow M_{i} \ldots\right\}$ is equal to $M\left\{x_{1} \leftarrow y_{1}\right\} \ldots\left\{x_{n} \leftarrow y_{n}\right\}\left\{y_{1} \leftarrow\right.$ $\left.M_{1}\right\} \ldots\left\{y_{n} \leftarrow M_{n}\right\}$, where the $y_{i}$ are fresh. To support this reduction, we first show the stability of the typing judgement under substitution of one variable by a fresh variable.

Lemma B.11. If $\Gamma+\{x: \tau\} \vdash M: \tau / \gamma[x \mapsto d]$ and $y \notin F V(M)$, then $\Gamma+\{y: \tau\} \vdash$ $M\{x \leftarrow y\}: \tau / \gamma[y \mapsto d]$.

Proof. Easy induction on the typing derivation of $M$.
Lemma B.12. (Parallel substitution.) Assume $\Gamma+\left\{\ldots x_{i}: \tau_{i} \ldots\right\} \vdash M: \tau /$ $\gamma_{M}\left[\ldots x_{i} \mapsto d_{i} \ldots\right]$, and for all $j \in\{1 \ldots n\}, \Gamma \vdash M_{j}: \tau_{j} / \gamma_{j}$ with for all $i, j$, $x_{i} \notin F V\left(M_{j}\right) \cup \operatorname{dom}\left(\gamma_{j}\right)$. Then, $\Gamma \vdash M\left\{\ldots x_{i} \leftarrow M_{i} \ldots\right\}: \tau / \gamma_{M} \wedge \bigwedge_{i} d_{i} @ \gamma_{i}$.

Proof. Write $M\left\{\ldots x_{i} \leftarrow M_{i} \ldots\right\}$ as $M\left\{x_{1} \leftarrow y_{1}\right\} \ldots\left\{x_{n} \leftarrow y_{n}\right\}\left\{y_{1} \leftarrow\right.$ $\left.M_{1}\right\} \ldots\left\{y_{n} \leftarrow M_{n}\right\}$ where the $y_{i}$ are fresh. We first apply lemma B. $11 n$ times to obtain $\Gamma+\left\{\ldots y_{i}: \tau_{i} \ldots\right\} \vdash M\left\{x_{1} \leftarrow y_{1}\right\} \ldots\left\{x_{n} \leftarrow y_{n}\right\}: \tau / \gamma_{M}\left[\ldots y_{i} \mapsto d_{i} \ldots\right]$. We then apply lemma B. $10 n$ times again, successively using the $n$ typing hypotheses for the $M_{i}$. This leads to the desired judgment.

## B. 4 Substitution by a variable

We now state and prove a stronger variant of lemma B. 10 for the case where we substitute a variable by another variable. This alternate substitution lemma is distinct from lemma B.11: here, $y$ is not supposed to be fresh, and this is why former occurences of $y$ must be taken into account, which is done through the $\wedge$ operation.

Lemma B.13. (Substitution by a variable.) If $\Gamma+\left\{x \mapsto \tau^{\prime}\right\} \vdash M: \tau / \gamma[x \mapsto d]$ and $\Gamma(y)=\tau^{\prime}$, then $\Gamma \vdash M\{x \leftarrow y\}: \tau / \gamma \wedge(y \mapsto d)$.

Proof. We write $\Gamma^{\prime}=\Gamma+\left\{x \mapsto \tau^{\prime}\right\}$ and $M^{\prime}=M\{x \leftarrow y\}$ and proceed by induction on the typing derivation of $M$ and case analysis on the last typing rule used.

Rule (var) We distinguish the three sub-cases $M=x, M=y$, and $M=z$ with $z \neq x$ and $z \neq y$. All three cases are straightforward.

Rule (abstr), $M=\lambda z \cdot M_{1}$ where $z$ is fresh. By typing hypothesis, we have

$$
\Gamma^{\prime}+\left\{z \mapsto \tau_{1}\right\} \vdash M_{1}: \tau_{2} /(\gamma[x \mapsto d]-1)\left[z \mapsto d_{0}\right]
$$

with $\tau=\tau_{1} \xrightarrow{d_{0}} \tau_{2}$. This is equivalent to

$$
\Gamma^{\prime}+\left\{z \mapsto \tau_{1}\right\} \vdash M_{1}: \tau_{2} /(\gamma-1)\left[z \mapsto d_{0}\right][x \mapsto d-1] .
$$

Applying the induction hypothesis, we then have

$$
\Gamma+\left\{z \mapsto \tau_{1}\right\} \vdash M_{1}\{x \leftarrow y\}: \tau_{2} /(\gamma-1)\left[z \mapsto d_{0}\right] \wedge(y \mapsto d-1)
$$

which yields

$$
\Gamma+\left\{z \mapsto \tau_{1}\right\} \vdash M_{1}\{x \leftarrow y\}: \tau_{2} /((\gamma \wedge(y \mapsto d))-1)\left[z \mapsto d_{0}\right] .
$$

We conclude $\Gamma \vdash M\{x \leftarrow y\}: \tau / \gamma \wedge(y \mapsto d)$ by rule (abstr).
Rule (app), $M=M_{1} M_{2}$. The typing hypothesis entails $\Gamma^{\prime} \vdash M_{1}: \tau^{\prime} \xrightarrow{d_{0}} \tau / \gamma_{1}$ and $\Gamma^{\prime} \vdash M_{2}: \tau^{\prime} / \gamma_{2}$ with $\gamma[x \mapsto d]=\left(\gamma_{1}-1\right) \wedge d_{0} @ \gamma_{2}$. Take $\gamma_{1}^{\prime}=\gamma_{1}[x \mapsto \gamma(x)+1]$ and $\gamma_{2}^{\prime}=\gamma_{2}[x \mapsto \infty]$. These degree environments enjoy the following properties:
$\gamma_{1}=\gamma_{1}^{\prime}\left[x \mapsto \gamma_{1}(x)\right] \quad \gamma_{2}=\gamma_{2}^{\prime}\left[x \mapsto \gamma_{2}(x)\right] \quad \gamma=\left(\gamma_{1}^{\prime}-1\right) \wedge d_{0} @ \gamma_{2}^{\prime}$.
ACM Transactions on Programming Languages and Systems, Vol. 27, No. 5, September 2005.

By induction hypothesis, we can derive

$$
\begin{gathered}
\Gamma \vdash M_{1}\{x \leftarrow y\}: \tau^{\prime \prime} \xrightarrow{d_{0}} \tau / \gamma_{1}^{\prime} \wedge\left(y \mapsto \gamma_{1}(x)\right) \\
\Gamma \vdash M_{2}\{x \leftarrow y\}: \tau^{\prime \prime} / \gamma_{2}^{\prime} \wedge\left(y \mapsto \gamma_{2}(x)\right) \\
\Gamma \vdash M^{\prime}: \tau /\left(\gamma_{1}^{\prime}-1\right) \wedge\left(y \mapsto\left(\gamma_{1}(x)-1\right)\right) \wedge d_{0} @\left(\gamma_{2}^{\prime} \wedge\left(y \mapsto \gamma_{2}(x)\right)\right)
\end{gathered}
$$

The degree environment in the conclusion is equal to

$$
\left(\gamma_{1}^{\prime}-1\right) \wedge d_{0} @ \gamma_{2}^{\prime} \wedge\left(y \mapsto\left(\left(\gamma_{1}(x)-1\right) \wedge d_{0} @ \gamma_{2}(x)\right)\right)=\gamma \wedge(y \mapsto d)
$$

The desired result follows.
Rule (appvar), $M=M_{1} z$ We have $\Gamma^{\prime} \vdash M_{1}: \tau^{\prime \prime} \xrightarrow{d_{0}} \tau / \gamma_{1}$ and $\Gamma^{\prime}(z)=\tau^{\prime \prime}$ and $\gamma[x \mapsto d]=\left(\gamma_{1}-1\right) \wedge\left(z \mapsto d_{0}\right)$. We consider the two cases $z=x$ and $z \neq x$ separately.

Case $z=x$. In this case, $\tau^{\prime}=\tau^{\prime \prime}$. Consider $\gamma_{1}^{\prime}=\gamma_{1}[x \mapsto \gamma(x)+1]$. We have $\gamma_{1}^{\prime}-1=\gamma$ and $\gamma_{1}^{\prime}\left[x \mapsto \gamma_{1}(x)\right]=\gamma_{1}$. By induction hypothesis, we obtain

$$
\Gamma \vdash M_{1}\{x \leftarrow y\}: \tau^{\prime} \xrightarrow{d_{0}} \tau / \gamma_{1}^{\prime} \wedge\left(y \mapsto \gamma_{1}(x)\right) .
$$

Since $\Gamma(y)=\tau^{\prime}$, rule (appvar) concludes

$$
\Gamma \vdash M^{\prime}: \tau /\left(\gamma_{1}^{\prime}-1\right) \wedge\left(y \mapsto\left(\gamma_{1}(x)-1\right)\right) \wedge\left(y \mapsto d_{0}\right) .
$$

The degree environment in this conclusion is equal to $\left(\gamma_{1}^{\prime}-1\right) \wedge\left(y \mapsto\left(\left(\gamma_{1}(x)-1\right) \wedge d_{0}\right)\right)$, that is, $\gamma \wedge(y \mapsto d)$. This is the expected result.

Case $z \neq x$. Define $\gamma_{1}^{\prime}=\gamma_{1}[x \mapsto \gamma(x)+1]$. We have $\gamma=\left(\gamma_{1}^{\prime}-1\right) \wedge\left(z \mapsto d_{0}\right)$ and $\gamma_{1}^{\prime}\left[x \mapsto \gamma_{1}(x)\right]=\gamma_{1}$. By induction hypothesis, we obtain

$$
\Gamma \vdash M_{1}\{x \leftarrow y\}: \tau^{\prime \prime} \xrightarrow{d_{0}} \tau / \gamma_{1}^{\prime} \wedge\left(y \mapsto \gamma_{1}(x)\right) .
$$

Since $\Gamma(z)=\tau^{\prime \prime}$, we derive by rule (appvar)

$$
\Gamma \vdash M^{\prime}: \tau /\left(\gamma_{1}^{\prime}-1\right) \wedge\left(y \mapsto\left(\gamma_{1}(x)-1\right)\right) \wedge\left(z \mapsto d_{0}\right) .
$$

The latter degree environment is equal to $\gamma \wedge\left(y \mapsto\left(\gamma_{1}(x)-1\right)\right)$, that is, $\gamma \wedge(y \mapsto d)$, as required to establish the result.

Rule (rec), $M=$ let rec $\ldots x_{i}=M_{i} \ldots$ in $N$ where the $x_{i}$ are fresh. The premises of rule (rec) hold:

$$
\begin{gathered}
\Gamma^{\prime}+\left\{\ldots x_{i}: \tau_{i} \ldots\right\} \vdash M_{j}: \tau_{j} / \gamma_{j}\left[\ldots x_{j} \mapsto d_{j i} \ldots\right] \text { for all } j \\
\Gamma^{\prime}+\left\{\ldots x_{i}: \tau_{i} \ldots\right\} \vdash N: \tau / \gamma_{N}\left[\ldots x_{i} \mapsto d_{i} \ldots\right] \\
\text { for all } i, j, d_{i j} \geq 1 \\
\text { for all } i, j, k, d_{i k} \leq d_{i j} @ d_{j k} .
\end{gathered}
$$

Moreover, $\gamma[x \mapsto d]=\gamma_{N} \wedge\left(\bigwedge_{i} d_{i} @ \gamma_{i}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ \gamma_{j}\right)$. By lemma B.6, we can construct $\gamma_{N}^{\prime}$ and $\gamma_{i}^{\prime}$ for each $i$ satisfying the following conditions: $\gamma=\gamma_{N}^{\prime} \wedge$ $\left(\bigwedge_{i} d_{i} @ \gamma_{i}^{\prime}\right) \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ \gamma_{j}^{\prime}\right), \gamma_{N}=\gamma_{N}^{\prime}\left[x \mapsto d_{N}\right]$, and for all $i, \gamma_{i}=\gamma_{i}^{\prime}\left[x \mapsto d_{i}^{\prime}\right]$,
with $d_{N}=\gamma_{N}(x)$ and for all $i, d_{i}^{\prime}=\gamma_{i}(x)$. Applying the induction hypothesis, we obtain derivations for the following judgments:

$$
\begin{aligned}
\Gamma+ & \left\{\ldots x_{i}: \tau_{i} \ldots\right\} \vdash M_{j}\{x \leftarrow y\}: \tau_{j} / \gamma_{j}^{\prime}\left[\ldots x_{i} \mapsto d_{j i} \ldots\right] \wedge\left(y \mapsto d_{j}^{\prime}\right) \text { for all } j \\
& \Gamma+\left\{\ldots x_{i}: \tau_{i} \ldots\right\} \vdash N\{x \leftarrow y\}: \tau / \gamma_{N}^{\prime}\left[\ldots x_{i} \mapsto d_{i} \ldots\right] \wedge\left(y \mapsto d_{N}\right) .
\end{aligned}
$$

From these premises, rule (rec) derives $\Gamma \vdash M^{\prime}: \tau / \gamma^{\prime}$, where

$$
\begin{aligned}
\gamma^{\prime}= & \gamma_{N}^{\prime} \wedge\left(y \mapsto d_{N}\right) \\
& \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @\left(\gamma_{j}^{\prime} \wedge\left(y \mapsto d_{j}^{\prime}\right)\right)\right) \\
& \wedge\left(\bigwedge_{i} d_{i} @\left(\gamma_{i}^{\prime} \wedge\left(y \mapsto d_{i}^{\prime}\right)\right)\right) \\
= & \gamma \wedge\left(y \mapsto\left(d_{N} \wedge\left(\bigwedge_{i, j} d_{i} @ d_{i j} @ d_{j}^{\prime}\right) \wedge\left(\bigwedge_{i} d_{i} @ d_{i}^{\prime}\right)\right)\right) \\
= & \gamma \wedge(y \mapsto d)
\end{aligned}
$$

This concludes the proof.

## B. 5 Soundness

The soundness of $\lambda_{B}$ 's type system (theorem 5.1) is, as usual, a corollary of two properties: subject reduction (lemma B.15) and progress (lemma B.16). We start with a technical lemma on recursive definitions arising from the reduction of a let rec term.

Lemma B.14. Assume $\Gamma+\left\{\ldots x_{i}: \tau_{i} \ldots\right\} \vdash M_{j}: \tau_{j} / \gamma_{j}\left[\ldots x_{i} \mapsto d_{j i} \ldots\right]$ for all $j \in\{1 \ldots n\}$. Further assume that for all $i, j, d_{i j} \geq 1$ and for all $i, j, k$, $d_{i k} \leq d_{i j} @ d_{j k}$. Then, for any $i_{0} \in\{1 \ldots n\}$,

$$
\Gamma \vdash \text { let rec } \ldots x_{i}=M_{i} \ldots \text { in } M_{i_{0}}: \tau_{i_{0}} / \gamma_{i_{0}} \wedge \bigwedge_{i} d_{i_{0} i} @ \gamma_{i}
$$

Proof. By application of rule (rec), we obtain

$$
\Gamma \vdash \text { let rec } \ldots x_{i}=M_{i} \ldots \text { in } M_{i_{0}}: \tau_{i_{0}} / \gamma_{i_{0}} \wedge \bigwedge_{i, j} d_{i_{0} i} @ d_{i j} @ \gamma_{j} \wedge \bigwedge_{i} d_{i_{0} i} @ \gamma_{i} .
$$

Since $d_{i_{0} j} \leq d_{i_{0} i} @ d_{i j}$, we have $d_{i_{0} j} @ \gamma_{j} \leq d_{i_{0} i} @ d_{i j} @ \gamma_{j}$. Thus,

$$
\bigwedge_{i, j} d_{i_{0} i} @ d_{i j} @ \gamma_{j} \wedge \bigwedge_{i} d_{i_{0} i} @ \gamma_{i}=\bigwedge_{i} d_{i_{0} i} @ \gamma_{i}
$$

and the expected result follows.
Lemma B.15. (Subject reduction.) If $\Gamma \vdash M: \tau / \gamma$ and $M \rightarrow M^{\prime}$, then $\Gamma \vdash M^{\prime}: \tau / \gamma$.

Proof. The proof is by case analysis on the reduction rule used.
Reduction rule (beta), $M=\left(\lambda x \cdot M_{1}\right) v$. The typing derivation for $M$ ends either with an application of the (app) rule or with the (appvar) rule.

In the (appvar) case, we have $v=y$. We rename $x$ if necessary to ensure $x \neq y$. The typing derivation for $M$ is of the following form

$$
\frac{\frac{\Gamma+\left\{x \mapsto \tau^{\prime}\right\} \vdash M_{1}: \tau /\left(\gamma_{0}-1\right)[x \mapsto d]}{\Gamma \vdash \lambda x \cdot M_{1}: \tau^{\prime} \xrightarrow{d} \tau / \gamma_{0}}}{} \begin{gathered}
\Gamma \vdash M: \tau /\left(\gamma_{0}-1\right) \wedge(y \mapsto d) \\
\Gamma(y)=\tau^{\prime} \\
\end{gathered}
$$

Moreover, $\gamma=\left(\gamma_{0}-1\right) \wedge(y \mapsto d)$ and $M^{\prime}=M_{1}\{x \leftarrow y\}$. By lemma B.13, we have

$$
\Gamma \vdash M^{\prime}: \tau /\left(\gamma_{0}-1\right) \wedge(y \mapsto d)
$$

which is the expected result.
In the (app) case, the typing derivation for $M$ is

$$
\frac{\frac{\Gamma+\left\{x \mapsto \tau^{\prime}\right\} \vdash M_{1}: \tau /\left(\gamma_{1}-1\right)[x \mapsto d]}{\Gamma \vdash \lambda x \cdot M_{1}: \tau^{\prime} \xrightarrow{d} \tau / \gamma_{1}} \frac{\vdots}{\Gamma \vdash M: \tau /\left(\gamma_{1}-1\right) \wedge d @ \gamma_{2}} \frac{\Gamma \vdash v: \tau^{\prime} / \gamma_{2}}{\Gamma \vdash}}{\frac{\Gamma}{\Gamma}}
$$

Moreover, $M^{\prime}=M_{1}\{x \leftarrow v\}$ and $\gamma=\left(\gamma_{1}-1\right) \wedge d @ \gamma_{2}$. By lemma B.10, it follows that $\Gamma \vdash M^{\prime}: \tau / \gamma$, as expected.

Reduction rule (mutrec), $M=$ let rec $\ldots x_{i}=v_{i} \ldots$ in $N$, where the $x_{i}$ are fresh. We have $M^{\prime}=M\left\{\ldots x_{i} \leftarrow M_{i} \ldots\right\}$ with, for all $i, M_{i}=$ let rec $\ldots x_{j}=$ $v_{j} \ldots$ in $v_{i}$. By typing, we have

$$
\begin{gathered}
\begin{array}{r}
\Gamma+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash N: \tau / \gamma_{N}\left[\ldots x_{j} \mapsto d_{j} \ldots\right] \\
\text { for all } i, \Gamma+\left\{\ldots x_{j}: \tau_{j} \ldots\right\} \vdash v_{i}: \tau_{i} / \gamma_{i}\left[\ldots x_{j} \mapsto d_{i j} \ldots\right]
\end{array} \\
\text { for all } i, j, d_{i j} \geq 1
\end{gathered}
$$

By lemma B.14, it follows that

$$
\Gamma \vdash M_{i}: \tau_{i} / \gamma_{i} \wedge \bigwedge_{j} d_{i j} @ \gamma_{j} .
$$

By lemma B.12, we obtain

$$
\Gamma \vdash M^{\prime}: \tau / \gamma_{N} \wedge\left(\bigwedge_{i} d_{i} @\left(\gamma_{i} \wedge \bigwedge_{j} d_{i j} @ \gamma_{j}\right)\right)
$$

which is identical to the expected result

$$
\Gamma \vdash M^{\prime}: \tau / \gamma_{N} \wedge\left(\bigwedge_{i} d_{i} @ \gamma_{i}\right) \wedge\left(\bigwedge_{i j} d_{i} @ d_{i j} @ \gamma_{j}\right)
$$

Reduction rule (context), $M=\mathbb{E}\left[M_{1}\right], M_{1} \rightarrow M_{1}^{\prime}$ and $M^{\prime}=\mathbb{E}\left[M_{1}^{\prime}\right]$. The result follows by structural induction and case analysis over the context $\mathbb{E}$. The only point worth mentioning is that in the case $\mathbb{E}=v[]$ and the typing derivation ends with rule (appvar), then $M_{1}$ can only be a variable, and therefore cannot reduce.

Lemma B.16. (Progress.) If $\Gamma \vdash M: \tau / \gamma$ and $\gamma \geq 1$, then either $M$ is a value, or there exists $M^{\prime}$ such that $M \rightarrow M^{\prime}$.

Proof. The proof is a standard inductive argument on the typing derivation of $M$, and case analysis on the last typing rule used.

Rule (var). $M$ is a variable, i.e. a value.
Rule (abstr). $M$ is a $\lambda$-abstraction, i.e. a value.
Rule (app), $M=M_{1} M_{2}$. We have $\Gamma \vdash M_{1}: \tau^{\prime} \xrightarrow{d} \tau / \gamma_{1}$ and $\Gamma \vdash M_{2}: \tau^{\prime} / \gamma_{2}$. Moreover, $\gamma=\left(\gamma_{1}-1\right) \wedge d @ \gamma_{2}$. Applying the induction hypothesis to $M_{1}$ and $M_{2}$, either both terms are values or at least one reduces. If $M_{1}$ reduces, $M$ also reduces via the context [] $M_{2}$. If $M_{1}$ is a value and $M_{2}$ reduces, $M$ also reduces via the context $M_{1}$ []. If both $M_{1}$ and $M_{2}$ are values, the type $\tau^{\prime} \xrightarrow{d} \tau$ of $M_{1}$ guarantees that $M_{1}$ is either a variable or an abstraction. But $M_{1}$ cannot be a variable, because $\gamma \geq 1$ implies $\gamma_{1} \geq 2$. Hence, $M_{1}$ is an abstraction and we can apply rule (beta) to reduce $M$.
Rule (appvar). Same reasoning as in the (app) case.
Rule (rec), $M=$ let rec $\ldots x_{i}=M_{i} \ldots$ in $N$. If all $M_{i}$ are values, $M$ reduces by rule (mutrec). Otherwise, $M$ reduces via the rule (context).

## C. SOUNDNESS OF THE TRANSLATION

We now turn to proving the type soundness of the translation: the translation of a well-typed source term is a well-typed $\lambda_{B}$-term.

We start by stating three typing rules that are admissible in $\lambda_{B}$, and help typecheck the terms arising from the translation scheme. We omit the proofs of admissibility, which are straightforward.

Lemma C.1. (Single let rec.) The following typing rule is admissible for the type system of $\lambda_{B}$.

$$
\frac{\Gamma+\left\{x \mapsto \tau^{\prime}\right\} \vdash M: \tau / \gamma_{1}[x \mapsto d] \quad \Gamma+\left\{x \mapsto \tau^{\prime}\right\} \vdash N: \tau^{\prime} / \gamma_{2}\left[x \mapsto d^{\prime}\right] \quad d^{\prime} \geq 1}{\Gamma \vdash \text { let rec } x=N \text { in } M: \tau / \gamma_{1} \wedge d @ \gamma_{2}}
$$

Lemma C.2. (Multiple abstractions.) The following typing rule is admissible for the type system of $\lambda_{B}$.

$$
\frac{\Gamma+\left\{\ldots x_{i}: \tau_{i} \ldots\right\} \vdash M: \tau /(\gamma-n)\left[\ldots x_{i} \mapsto d_{i} \ldots\right]}{\Gamma \vdash \vec{\lambda}\left(x_{1}, \ldots, x_{n}\right) . M: \tau_{1} \xrightarrow{d_{1}+(n-1)} \tau_{2} \xrightarrow{d_{2}+(n-2)} \ldots \tau_{n} \xrightarrow{d_{n}} \tau / \gamma}
$$

Lemma C.3. (Multiple applications.) The following typing rule is admissible for the type system of $\lambda_{B}$.

$$
\frac{\Gamma \vdash M: \tau_{1} \xrightarrow{d_{1}+(n-1)} \tau_{2} \xrightarrow{d_{2}+(n-2)} \ldots \tau_{n} \xrightarrow{d_{n}} \tau / \gamma \quad \Gamma\left(x_{i}\right)=\tau_{i} \text { for } i=1, \ldots, n}{\Gamma \vdash M\left(x_{1}, \ldots, x_{n}\right): \tau /(\gamma-n) \wedge\left(\ldots x_{i} \mapsto d_{i} \ldots\right)}
$$

We now prove two technical lemmas on the typing of sub-expressions that occur when translating the close and freeze operators.

Lemma C.4. (Translation of close.) Assume $\Gamma \vdash e: \llbracket\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\} \rrbracket / d^{o}(\Gamma)$. Let $X_{1}, \ldots, X_{n}$ be names such that $\overline{X_{i}} \notin \operatorname{dom}(\Gamma)$ and $\mathcal{O}\left(X_{i}\right)=\mathcal{I}\left(X_{i}\right)$ and $\mathcal{D}\left(X_{i}, X_{j}\right) \neq$ 0 for $i, j \in\{1, \ldots, n\}$. Further assume that for all immediate predecessors $X$ of one of the $X_{i}$ in $\mathcal{D}$, either $X$ is one of the $X_{i}$, or $\Gamma(\bar{X})=\mathcal{I}(X)$. Let $M$ be an expression and $\tau$ be a type such that $\Gamma^{\prime} \vdash M: \tau / d^{o}\left(\Gamma^{\prime}\right)$, where $\Gamma^{\prime}=\Gamma+\left\{\overline{X_{1}}\right.$ : $\left.\mathcal{O}\left(X_{1}\right), \ldots, \overline{X_{n}}: \mathcal{O}\left(X_{n}\right)\right\}$. Then,

$$
\Gamma \vdash \text { let rec } \ldots \overline{X_{i}}=e . X_{i} \overline{\mathcal{D}^{-1}\left(X_{i}\right)} \ldots \text { in } M: \tau / d^{o}(\Gamma)
$$

Proof. By definition of the translation of a mixin signature, and the hypotheses on $\Gamma$, the conditions of lemma C. 3 are met, and we obtain

$$
\Gamma^{\prime} \vdash e . X_{i} \overline{\mathcal{D}^{-1}\left(X_{i}\right)}: \mathcal{O}\left(X_{i}\right) / d^{o}(\Gamma) \wedge\left(\bar{X} \mapsto D\left(X, X_{i}\right) \mid X \in \mathcal{D}^{-1}\left(X_{i}\right)\right)
$$

Since $\overline{X_{j}} \notin \operatorname{dom}(\Gamma)$ for all $j$, the degree environment above is pointwise greater or equal to $d^{o}(\Gamma)\left[\overline{X_{j}} \mapsto D\left(X_{j}, X_{i}\right) \mid j \in\{1, \ldots, n\}\right]$. Thus, by lemma B.7, it follows that

$$
\Gamma^{\prime} \vdash e . X_{i} \overline{\mathcal{D}^{-1}\left(X_{i}\right)}: \mathcal{O}\left(X_{i}\right) / d^{o}(\Gamma)\left[\overline{X_{j}} \mapsto D\left(X_{j}, X_{i}\right) \mid j \in\{1, \ldots, n\}\right] .
$$

Moreover, $D\left(X_{j}, X_{i}\right) \in\{1, \infty\}$ for all $i$ and $j$. Hence, the premises of the (rec) typing rule are met. Applying the weakening lemma B. 7 to its conclusion, we obtain the desired result.

Lemma C.5. (Translation of freeze.) Assume $\Gamma \vdash e: \llbracket\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\} \rrbracket / d^{o}(\Gamma)$, where $e$ is a variable distinct from $\bar{X}$ for all names $X$. Let $X$ be a name such that $\mathcal{I}(X)=\mathcal{O}(X)$. Write $\mathcal{D}^{\prime}=D!X$ and $\mathcal{I}^{\prime}=\mathcal{I}_{\backslash X}$. Then, for all names $Y \in \operatorname{dom}(\mathcal{O})$, if $X \notin \mathcal{D}^{-1}(Y)$ we have

$$
\Gamma \vdash e . Y: \llbracket \mathcal{O}(Y) \rrbracket_{Y, \mathcal{D}^{\prime}, \mathcal{I}^{\prime}} / d^{o}(\Gamma)
$$

and if $X \in \mathcal{D}^{-1}(Y)$, we have
$\Gamma \vdash \vec{\lambda} \overline{\mathcal{D}^{\prime-1}(Y)}$. let rec $\bar{X}=e . X \overline{\mathcal{D}^{-1}(X)}$ in $e . Y \overline{\mathcal{D}^{-1}(Y)}: \llbracket \mathcal{O}(Y) \rrbracket_{Y, \mathcal{D}^{\prime}, \mathcal{I}^{\prime}} / d^{o}(\Gamma)$
Proof. Recall the definition of $\mathcal{D}^{\prime}$ :

$$
\mathcal{D}^{\prime}=\mathcal{D}!X=\left(\mathcal{D} \cup \mathcal{D}_{\text {around }}\right) \backslash \mathcal{D}_{\text {remove }}
$$

where $\mathcal{D}_{\text {around }}=\left\{Z \xrightarrow{\chi_{1}^{\prime} \wedge \chi_{2}^{\prime}} Y \mid\left(Z \xrightarrow{\chi_{1}} X\right) \in \mathcal{D},\left(X \xrightarrow{\chi_{2}} Y\right) \in \mathcal{D}\right\}$ and $\mathcal{D}_{\text {remove }}=$ $\{X \xrightarrow{\chi} Y \mid Y \in$ Names, $\chi \in\{0,1\}\}$.
Thus, in the case $X \notin \mathcal{D}^{-1}(Y)$, no edges leading to $Y$ are added nor removed. Hence, $\mathcal{D}^{\prime-1}(Y)=\mathcal{D}^{-1}(Y)$, which implies $\llbracket \mathcal{O}(X) \rrbracket_{X, \mathcal{D}!X, \mathcal{I}_{X}}=\llbracket \mathcal{O}(X) \rrbracket_{X, \mathcal{D}, \mathcal{I}}$ and the expected result.

Consider now the case $X \in \mathcal{D}^{-1}(Y)$. We have $\mathcal{D}^{\prime-1}(Y)=\left(\mathcal{D}^{-1}(Y) \cup \mathcal{D}^{-1}(X)\right) \backslash$ $\{X\}$. Define $\Gamma^{\prime}=\Gamma+\left\{\bar{Z}: \llbracket \mathcal{I}(Z) \rrbracket \mid Z \in \mathcal{D}^{-1}(Y)\right\}$. By lemma C.3, and using the fact that $e$ is not one of the $\bar{Z}$, it follows that

$$
\Gamma^{\prime} \vdash e . X \overline{\mathcal{D}^{-1}(X)}: \llbracket \mathcal{O} X \rrbracket /\left\{e \mapsto 0 ; \bar{Z} \mapsto \mathcal{D}(Z, X) \mid Z \in \mathcal{D}^{-1}(X)\right\}
$$

and

$$
\Gamma^{\prime}+\{\bar{X}: \llbracket \mathcal{I}(X) \rrbracket\} \vdash e . Y \overline{\overline{\mathcal{D}}^{-1}(Y)}: \llbracket \mathcal{O} Y \rrbracket /\left\{e \mapsto 0 ; \bar{Z} \mapsto \mathcal{D}(Z, Y) \mid Z \in \mathcal{D}^{-1}(Y)\right\} .
$$

Notice that $\mathcal{D}(X, X) \geq 1$, because otherwise the graph $\mathcal{D}$ would not be safe, making the signature $\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\}$ ill-formed. In addition, $\mathcal{O}(X)=\mathcal{I}(X)$. The conditions of lemma C. 1 are therefore met, and we obtain $\Gamma^{\prime} \vdash$ let rec $\bar{X}=$ $e . X \overline{\mathcal{D}^{-1}(X)}$ in $e . Y \overline{\mathcal{D}^{-1}(Y)}: \llbracket \mathcal{O}(Y) \rrbracket / \gamma$, where

$$
\begin{aligned}
\gamma= & \left\{e \mapsto 0 ; \bar{Z} \mapsto \mathcal{D}(Z, X) \mid Z \neq X, Z \in \mathcal{D}^{-1}(X)\right\} \\
& \wedge\left\{e \mapsto 0 ; \bar{Z} \mapsto \mathcal{D}(Z, Y) \mid Z \neq X, Z \in \mathcal{D}^{-1}(Y)\right\}
\end{aligned}
$$

By definition of $\mathcal{D}^{\prime}=\mathcal{D}!X, \gamma$ is equal to $\left\{e \mapsto 0 ; \bar{Z} \mapsto \mathcal{D}^{\prime}(Z, Y) \mid Z \in \mathcal{D}^{\prime-1}(Y)\right\}$. Applying lemma C.2, we obtain
$\Gamma \vdash \vec{\lambda} \overline{\mathcal{D}^{\prime-1}(Y)}$. let rec $\bar{X}=e . X \overline{\mathcal{D}^{-1}(X)}$ in $e . Y \overline{\mathcal{D}^{-1}(Y)}: \llbracket \mathcal{O}(X) \rrbracket_{X, \mathcal{D}^{\prime}, \mathcal{I}^{\prime}} /\{e \mapsto 0\}$ which implies the desired result by weakening.
Theorem C.6. (Soundness of the translation.) If $\Gamma \vdash E: \mathcal{T}$, then $\llbracket \Gamma \rrbracket \vdash \llbracket \bar{E} \rrbracket$ : $\llbracket \mathcal{T} \rrbracket / d^{o}(\Gamma)+\operatorname{IsRec}(E)$.

Proof. The proof is by structural induction on $E$, and case analysis on $E$.
Function abstraction: $E=\lambda x . C$ and $\mathcal{T}=\tau_{1} \rightarrow \tau_{2}$. By induction hypothesis, $\llbracket \Gamma \rrbracket+\left\{x: \tau_{1}\right\} \vdash \llbracket C \rrbracket: \tau_{2} / d^{o}(\Gamma)[x \mapsto 0]+I s R e c(C)$. Applying the degree weakening lemma if $\operatorname{IsRec}(C)$ is not zero, we obtain $\llbracket \Gamma \rrbracket+\left\{x: \tau_{1}\right\} \vdash \llbracket C \rrbracket: \tau_{2} / d^{o}(\Gamma)[x \mapsto 0]$. From this, the (abstr) typing rule shows that $\llbracket \Gamma \rrbracket \vdash \llbracket \lambda x . C \rrbracket: \tau_{1} \xrightarrow{0} \tau_{2} / d^{o}(\Gamma)+1$, which is the expected result since $\operatorname{IsRec}(\lambda x . C)=1$.
Other core language constructs: the result follows immediately from the induction hypothesis, since $\operatorname{IsRec}(E)=0$ in these cases.
Structure construction: $E=\langle\iota ; o\rangle$ and $\mathcal{T}=\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\}$. By typing, we have $\mathcal{D}=\mathcal{D}\langle\iota ; o\rangle, \vdash \mathcal{D}, \operatorname{dom}(o)=\operatorname{dom}(\mathcal{O})$, and for all $X \in \operatorname{dom}(o), \Gamma+\mathcal{I} \circ \iota \vdash o(X): \mathcal{O}(X)$.

Let $o=X_{i} \stackrel{i \in I}{\longmapsto} E_{i}, \mathcal{O}=X_{i} \stackrel{i \in I}{\mapsto} \mathcal{T}_{i}, \chi_{i}=\operatorname{IsRec}\left(E_{i}\right)$ and $\iota=y_{j} \stackrel{j \in J}{\mapsto} Y_{j}$, with $\mathcal{I}\left(Y_{j}\right)=\mathcal{T}_{j}^{\prime}$ for all $j$, with the $X_{i} \mathrm{~s}$ and $Y_{j} \mathrm{~s}$ ordered lexicographically, that is, if $i_{1}<i_{2}$, then $X_{i_{1}}<_{l e x} X_{i_{2}}$, and similarly for the $Y_{j} \mathrm{~s}$.

By induction hypothesis, for all $i$, we have $\llbracket \Gamma \rrbracket+\llbracket \mathcal{I} \circ \iota \rrbracket \vdash \llbracket \overline{E_{i}} \rrbracket: \llbracket \mathcal{T}_{i} \rrbracket / d^{o}(\Gamma+\mathcal{I} \circ$七) $+\chi_{i}$.
Notice that $F V\left(\llbracket \overline{E_{i}} \rrbracket\right)=F V\left(E_{i}\right)$ and $F V\left(E_{i}\right) \cap \operatorname{dom}(\iota)=\iota^{-1}\left(\mathcal{D}^{-1}\left(X_{i}\right)\right)$. We can therefore apply lemma C. 2 and weakening lemmas B. 8 and B. 9 to eliminate variables of $\operatorname{dom}(\iota)$ that are not free in $E_{i}$. Let $\left(Z_{1}, \ldots, Z_{n}\right)=\mathcal{D}^{-1}\left(X_{i}\right)$ and for all $k \in\{1 \ldots n\}, \mathcal{T}_{k}^{\prime \prime}=\mathcal{I}\left(Z_{k}\right)$. We obtain

$$
\Gamma \vdash \vec{\lambda}_{\iota}{ }^{-1}\left(\mathcal{D}^{-1}\left(X_{i}\right)\right) \cdot \llbracket \overline{E_{i}} \rrbracket: \llbracket \mathcal{T}_{1}^{\prime \prime} \rrbracket \xrightarrow{\chi_{i}+(n-1)} \ldots \llbracket \mathcal{T}_{n}^{\prime \prime} \rrbracket \xrightarrow{\chi_{i}} \llbracket \mathcal{T}_{i} \rrbracket / d^{o}(\Gamma)
$$

Moreover, we have $\llbracket \mathcal{T}_{i} \rrbracket_{X_{i}, \mathcal{D}, \mathcal{I}}=\llbracket \mathcal{T}_{1}^{\prime \prime} \rrbracket \xrightarrow{\chi_{i}+(n-1)} \ldots \llbracket \mathcal{T}_{n}^{\prime \prime} \rrbracket \xrightarrow{\chi_{i}} \llbracket \mathcal{T}_{i} \rrbracket$ as a consequence of $\mathcal{D}\left(Z_{k}, X_{i}\right)=\nu\left(\iota^{-1}\left(Z_{k}\right), E_{i}\right)=\operatorname{IsRec}\left(E_{i}\right)=\chi_{i}$. The desired result follows.
Closing: $E=\operatorname{close}\left(E^{\prime}\right)$ and $\mathcal{T}=\{\mathcal{I} ; \mathcal{O} ; \mathcal{D}\}$. We apply lemma C. 4 repeatedly to each let rec group in the translation, starting with the innermost one. Since the let rec are generated following a serialisation of the graph $\mathcal{D}$, all free variables in a let rec are bound earlier, and dependencies between the variables bound in the same let rec cannot have degree 0 (otherwise the graph $\mathcal{D}$ would not be safe, and $\mathcal{T}$ would be ill-formed). The expected result follows.

## App-18 <br> T. Hirschowitz and X.Leroy

Freezing: $E=E_{1}!X$. The result follows from the induction hypothesis applied to $E_{1}$, and lemma C. 5 applied to each component of the record generated by the translation.
Delete: $E=E_{1} \backslash X$. The result follows immediately from the induction hypothesis applied to $E_{1}$.

Renaming: $E=E_{1}[X \leftarrow Y]$. We apply the induction hypothesis to $E_{1}$, then use lemmas C. 2 and C. 3 to handle the rearrangement of the parameters of the record components.


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